

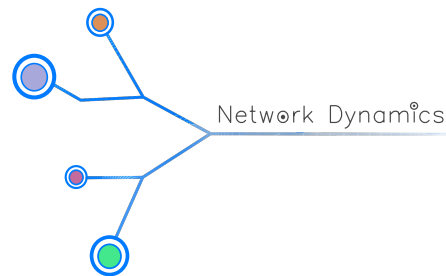


Contagion in Financial Networks

Author: Leonardo Massai

Advisors: Fabio Fagnani, Giacomo Como

Department of Mathematical Sciences (DISMA) , Politecnico di Torino





What the 2008 crisis taught us...

- High interconnectedness of modern financial system;
- default risk of a bank depends on the whole set of connections (network);
- the network topology can trigger default cascade and shock's amplification effects.

Main challenges

- Defining a network model that accounts for propagation effects;
- understanding how the topology affects systemic risk;



What the 2008 crisis taught us...

- High interconnectedness of modern financial system;
- default risk of a bank depends on the whole set of connections (network);
- the network topology can trigger default cascade and shock's amplification effects.

Main challenges

- Defining a network model that accounts for propagation effects;
- understanding how the topology affects systemic risk;



What the 2008 crisis taught us...

- High interconnectedness of modern financial system;
- default risk of a bank depends on the whole set of connections (network);
- the network topology can trigger default cascade and shock's amplification effects.

Main challenges

- Defining a network model that accounts for propagation effects;
- understanding how the topology affects systemic risk;



What the 2008 crisis taught us...

- High interconnectedness of modern financial system;
- default risk of a bank depends on the whole set of connections (network);
- the network topology can trigger default cascade and shock's amplification effects.

Main challenges

- Defining a network model that accounts for propagation effects;
- understanding how the topology affects systemic risk;



What the 2008 crisis taught us...

- High interconnectedness of modern financial system;
- default risk of a bank depends on the whole set of connections (network);
- the network topology can trigger default cascade and shock's amplification effects.

Main challenges

- Defining a network model that accounts for propagation effects;
- understanding how the topology affects systemic risk;

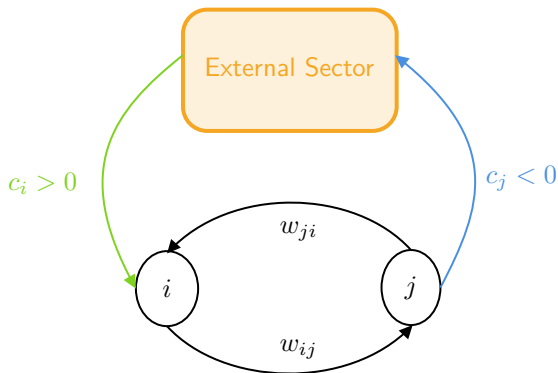


What the 2008 crisis taught us...

- High interconnectedness of modern financial system;
- default risk of a bank depends on the whole set of connections (network);
- the network topology can trigger default cascade and shock's amplification effects.

Main challenges

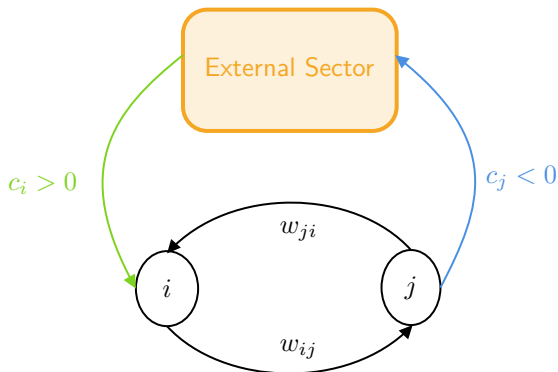
- Defining a network model that accounts for propagation effects;
- understanding how the topology affects systemic risk;



- w_{ij} inter-bank liability;
- $c_i > 0$ positive money inflow;
- $c_j < 0$ outside debt.

Everything is fine

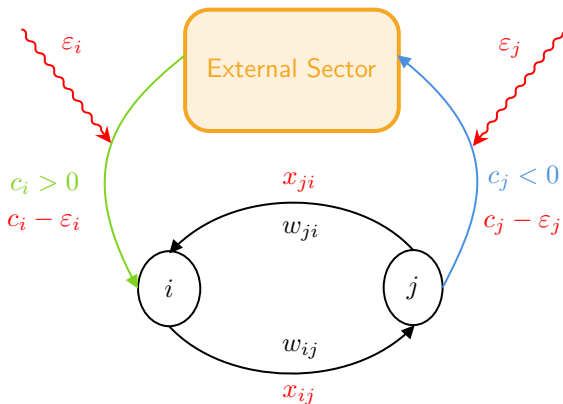
In normal conditions, every bank i can meet its total liability: $w_i = \sum_j w_{ij}$.



- w_{ij} inter-bank liability;
- $c_i > 0$ positive money inflow;
- $c_j < 0$ outside debt.

Everything is fine

In normal conditions, every bank i can meet its total liability: $w_i = \sum_j w_{ij}$.



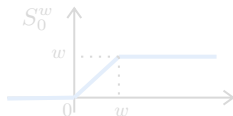
- Shocks ε hit the network by reducing c ;
- Nodes may default and not be able to pay their liabilities (direct effect);
- Shocks propagate across the network because of reduced payments (indirect effect).

Clearing Vectors

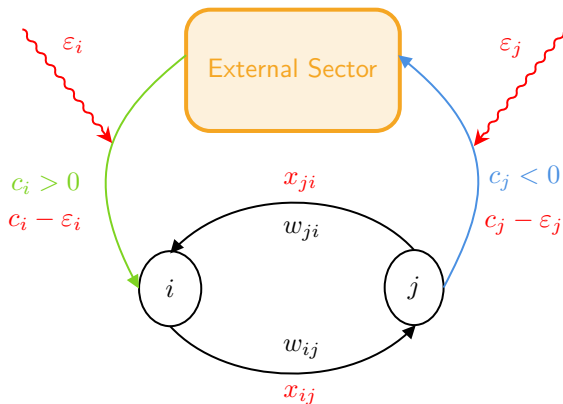
x is a set of consistent payments after the shock:

$$x = \mathcal{S}_0^w(P^\top x + c - \varepsilon)$$

where $(P)_{ij} = \frac{w_{ij}}{w_i}$ and \mathcal{S}_0^w is a saturation:



- Notice that any solution is such that $x \in \mathcal{L}_0^w := \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$



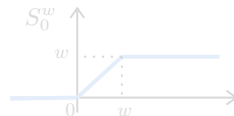
- Shocks ε hit the network by reducing c ;
- Nodes may default and not be able to pay their liabilities (direct effect);
- Shocks propagate across the network because of reduced payments (indirect effect).

Clearing Vectors

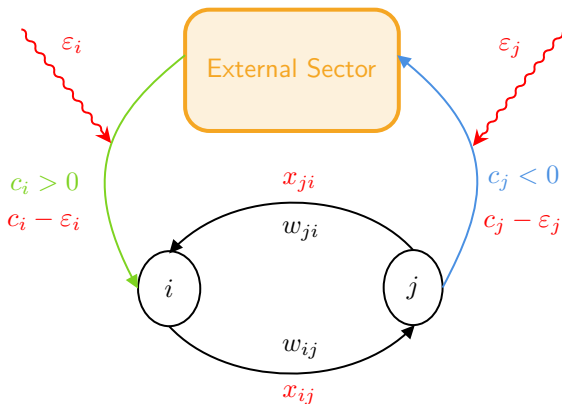
x is a set of consistent payments after the shock:

$$x = \mathcal{S}_0^w(P^\top x + c - \varepsilon)$$

where $(P)_{ij} = \frac{w_{ij}}{w_i}$ and \mathcal{S}_0^w is a saturation:



- Notice that any solution is such that $x \in \mathcal{L}_0^w := \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$



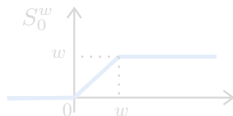
- Shocks ε hit the network by reducing c ;
- Nodes may default and not be able to pay their liabilities (direct effect);
- Shocks propagate across the network because of reduced payments (indirect effect).

Clearing Vectors

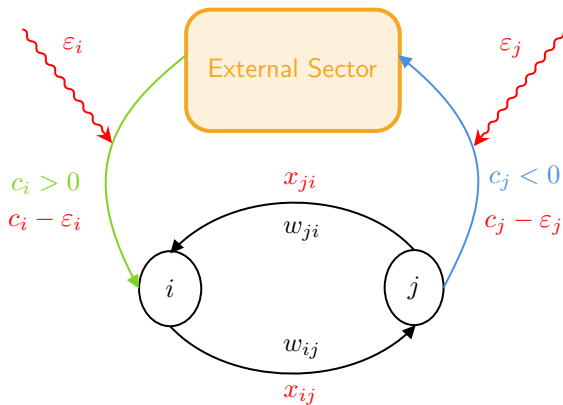
x is a set of consistent payments after the shock:

$$x = \mathcal{S}_0^w(P^\top x + c - \varepsilon)$$

where $(P)_{ij} = \frac{w_{ij}}{w_i}$ and \mathcal{S}_0^w is a saturation:



- Notice that any solution is such that $x \in \mathcal{L}_0^w := \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$



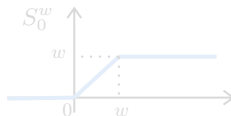
- Shocks ε hit the network by reducing c ;
- Nodes may default and not be able to pay their liabilities (direct effect);
- Shocks propagate across the network because of reduced payments (indirect effect).

Clearing Vectors

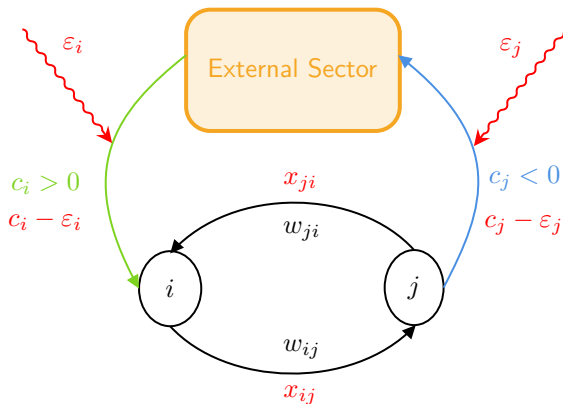
x is a set of consistent payments after the shock:

$$x = \mathcal{S}_0^w(P^\top x + c - \varepsilon)$$

where $(P)_{ij} = \frac{w_{ij}}{w_i}$ and \mathcal{S}_0^w is a saturation:



- Notice that any solution is such that $x \in \mathcal{L}_0^w := \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$



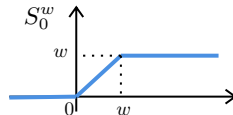
- Shocks ε hit the network by reducing c ;
- Nodes may default and not be able to pay their liabilities (direct effect);
- Shocks propagate across the network because of reduced payments (indirect effect).

Clearing Vectors

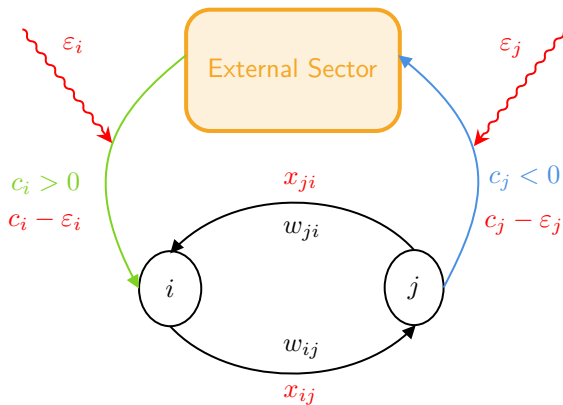
x is a set of consistent payments after the shock:

$$x = \mathcal{S}_0^w (P^\top x + c - \varepsilon)$$

where $(P)_{ij} = \frac{w_{ij}}{w_i}$ and \mathcal{S}_0^w is a saturation:



- Notice that any solution is such that $x \in \mathcal{L}_0^w := \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$



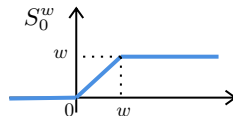
- Shocks ε hit the network by reducing c ;
- Nodes may default and not be able to pay their liabilities (direct effect);
- Shocks propagate across the network because of reduced payments (indirect effect).

Clearing Vectors

x is a set of consistent payments after the shock:

$$x = \mathcal{S}_0^w (P^\top x + c - \varepsilon)$$

where $(P)_{ij} = \frac{w_{ij}}{w_i}$ and \mathcal{S}_0^w is a saturation:



- Notice that any solution is such that $x \in \mathcal{L}_0^w := \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$

We study saturated equilibrium models in networks. Precisely, we consider the following fixed point equation

$$x_i = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}, \quad i = 1, \dots, n$$

or, more compactly,

$$x = S_0^w (P^\top x + c)$$

where:

- $(S_0^w(x))_i = \min \{ \max \{ x_i, 0 \}, w_i \}$, $i = 1, \dots, n$;
- $P \in \mathbb{R}_+^{n \times n}$ is a non-negative square matrix and $w \in \mathbb{R}_+^n$ that jointly describe the network;
- the solutions $x \in \mathcal{X}$ are called equilibria of the network (P, w) with exogenous flow c ;
- $x \in \mathcal{L}_0^w = \{x \in \mathbb{R}^n : 0 \leq x \leq w\}$

¹L. Massai, G. Como, and F. Fagnani. "Equilibria and Systemic Risk in Saturated Networks". In: *Mathematics of Operations Research* (2021). URL: <https://doi.org/10.1287/moor.2021.1188>.

Consider a set of players $\mathcal{V} = \{1, \dots, n\}$ playing an action $x_i \in [0, w_i]$ and with quadratic utility

$$u_i(x) = u_i(x_i, x_{-i}) = c_i x_i - \frac{x_i^2}{2} + x_i \sum_j P_{ji} x_j$$

- $P_{ij} \geq 0$ strength of interaction: games of pure strategic complements.

Quadratic utility \implies best response of a player i is always unique and given by

$$B_i(x_{-i}) = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}.$$

- Nash equilibria are exactly such that $x = S_0^w(P^\top x + c)$;
- more in general, our analysis applies to $u_i(x) = \varphi_i \left(x_i - c_i + \sum_{j \neq i} P_{ji} x_j \right)$ for a continuous $\varphi_i : \mathbb{R} \mapsto \mathbb{R}$ that is increasing on $(-\infty, 0]$ and decreasing in $[0, +\infty)$;
- these are *supermodular games* (increase of one player's action encourages the others to do so as well).

Consider a set of players $\mathcal{V} = \{1, \dots, n\}$ playing an action $x_i \in [0, w_i]$ and with quadratic utility

$$u_i(x) = u_i(x_i, x_{-i}) = c_i x_i - \frac{x_i^2}{2} + x_i \sum_j P_{ji} x_j$$

- $P_{ij} \geq 0$ strength of interaction: games of pure strategic complements.

Quadratic utility \implies best response of a player i is always unique and given by

$$B_i(x_{-i}) = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}.$$

- Nash equilibria are exactly such that $x = S_0^w(P^\top x + c)$;
- more in general, our analysis applies to $u_i(x) = \varphi_i \left(x_i - c_i + \sum_{j \neq i} P_{ji} x_j \right)$ for a continuous $\varphi_i : \mathbb{R} \mapsto \mathbb{R}$ that is increasing on $(-\infty, 0]$ and decreasing in $[0, +\infty)$;
- these are *supermodular games* (increase of one player's action encourages the others to do so as well).

Consider a set of players $\mathcal{V} = \{1, \dots, n\}$ playing an action $x_i \in [0, w_i]$ and with quadratic utility

$$u_i(x) = u_i(x_i, x_{-i}) = c_i x_i - \frac{x_i^2}{2} + x_i \sum_j P_{ji} x_j$$

- $P_{ij} \geq 0$ strength of interaction: games of pure strategic complements.

Quadratic utility \implies best response of a player i is always unique and given by

$$B_i(x_{-i}) = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}.$$

- Nash equilibria are exactly such that $x = S_0^w(P^\top x + c)$;
- more in general, our analysis applies to $u_i(x) = \varphi_i \left(x_i - c_i + \sum_{j \neq i} P_{ji} x_j \right)$ for a continuous $\varphi_i : \mathbb{R} \mapsto \mathbb{R}$ that is increasing on $(-\infty, 0]$ and decreasing in $[0, +\infty)$;
- these are *supermodular games* (increase of one player's action encourages the others to do so as well).

Network games with monotone linear saturated best responses



Consider a set of players $\mathcal{V} = \{1, \dots, n\}$ playing an action $x_i \in [0, w_i]$ and with quadratic utility

$$u_i(x) = u_i(x_i, x_{-i}) = c_i x_i - \frac{x_i^2}{2} + x_i \sum_j P_{ji} x_j$$

- $P_{ij} \geq 0$ strength of interaction: games of pure strategic complements.

Quadratic utility \implies best response of a player i is always unique and given by

$$B_i(x_{-i}) = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}.$$

- Nash equilibria are exactly such that $x = S_0^w(P^\top x + c)$;
- more in general, our analysis applies to $u_i(x) = \varphi_i \left(x_i - c_i + \sum_{j \neq i} P_{ji} x_j \right)$ for a continuous $\varphi_i : \mathbb{R} \mapsto \mathbb{R}$ that is increasing on $(-\infty, 0]$ and decreasing in $[0, +\infty)$;
- these are *supermodular games* (increase of one player's action encourages the others to do so as well).

Consider a set of players $\mathcal{V} = \{1, \dots, n\}$ playing an action $x_i \in [0, w_i]$ and with quadratic utility

$$u_i(x) = u_i(x_i, x_{-i}) = c_i x_i - \frac{x_i^2}{2} + x_i \sum_j P_{ji} x_j$$

- $P_{ij} \geq 0$ strength of interaction: games of pure strategic complements.

Quadratic utility \implies best response of a player i is always unique and given by

$$B_i(x_{-i}) = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}.$$

- Nash equilibria are exactly such that $x = S_0^w(P^\top x + c)$;
- more in general, our analysis applies to $u_i(x) = \varphi_i \left(x_i - c_i + \sum_{j \neq i} P_{ji} x_j \right)$ for a continuous $\varphi_i : \mathbb{R} \mapsto \mathbb{R}$ that is increasing on $(-\infty, 0]$ and decreasing in $[0, +\infty)$;
- these are *supermodular games* (increase of one player's action encourages the others to do so as well).

Network games with monotone linear saturated best responses



Consider a set of players $\mathcal{V} = \{1, \dots, n\}$ playing an action $x_i \in [0, w_i]$ and with quadratic utility

$$u_i(x) = u_i(x_i, x_{-i}) = c_i x_i - \frac{x_i^2}{2} + x_i \sum_j P_{ji} x_j$$

- $P_{ij} \geq 0$ strength of interaction: games of pure strategic complements.

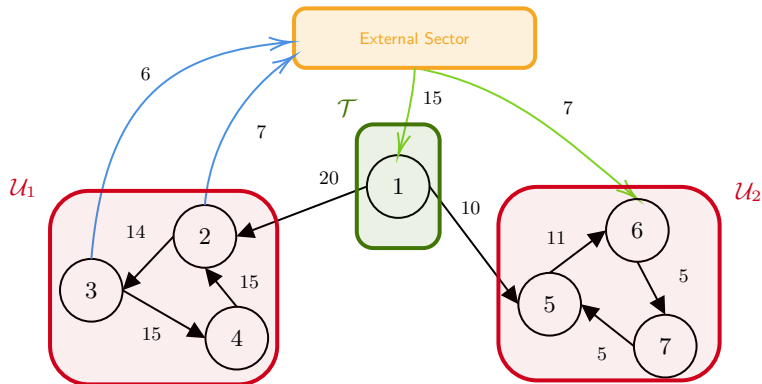
Quadratic utility \implies best response of a player i is always unique and given by

$$B_i(x_{-i}) = \min \left\{ \max \left\{ \sum_{j=1}^n x_j P_{ji} + c_i, 0 \right\}, w_i \right\}.$$

- Nash equilibria are exactly such that $x = S_0^w(P^\top x + c)$;
- more in general, our analysis applies to $u_i(x) = \varphi_i \left(x_i - c_i + \sum_{j \neq i} P_{ji} x_j \right)$ for a continuous $\varphi_i : \mathbb{R} \mapsto \mathbb{R}$ that is increasing on $(-\infty, 0]$ and decreasing in $[0, +\infty)$;
- these are *supermodular games* (increase of one player's action encourages the others to do so as well).

Example

$$\begin{cases} x(t+1) &= S_0^w (P^\top x(t) + c) \\ x(0) &= w \end{cases}$$

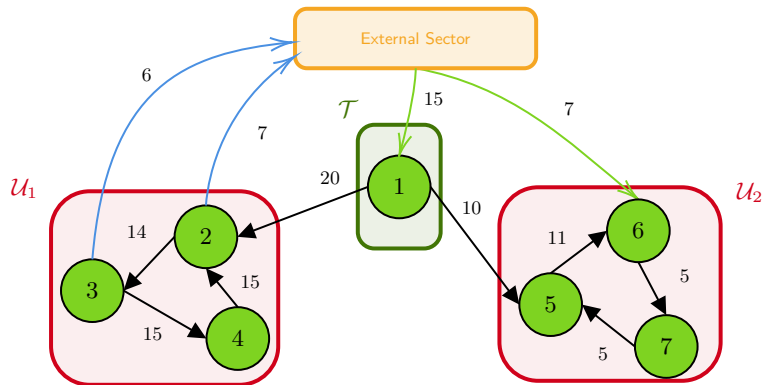


Example

$t = 0$



$$\begin{cases} x(t+1) = S_0^w (P^\top x(t) + c) \\ x(0) = w \end{cases}$$

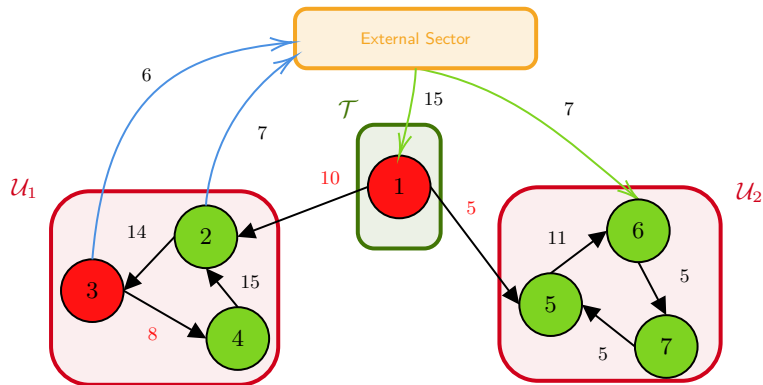


Example

$t = 1$



$$\begin{cases} x(t+1) = S_0^w (P^\top x(t) + c) \\ x(0) = w \end{cases}$$

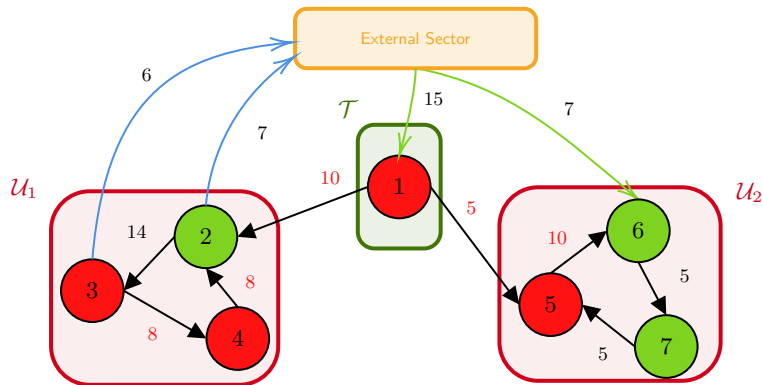


Example

$t = 2$



$$\begin{cases} x(t+1) = S_0^w (P^\top x(t) + c) \\ x(0) = w \end{cases}$$

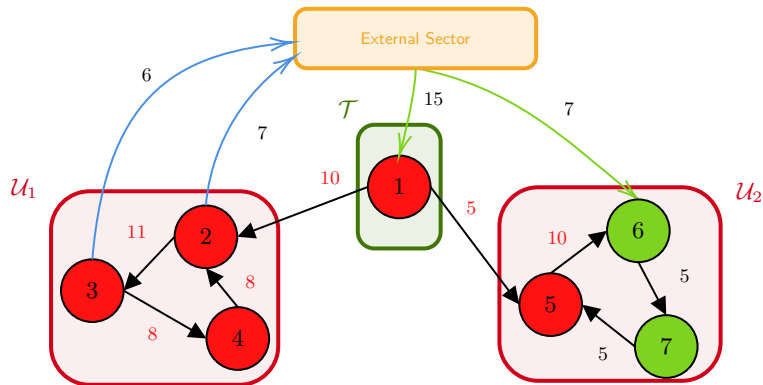


Example

$t = 3$



$$\begin{cases} x(t+1) = S_0^w (P^\top x(t) + c) \\ x(0) = w \end{cases}$$

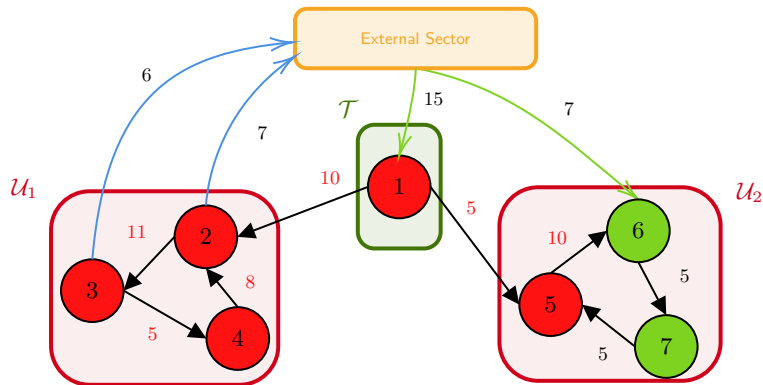


Example

$t = 4$



$$\begin{cases} x(t+1) = S_0^w (P^\top x(t) + c) \\ x(0) = w \end{cases}$$

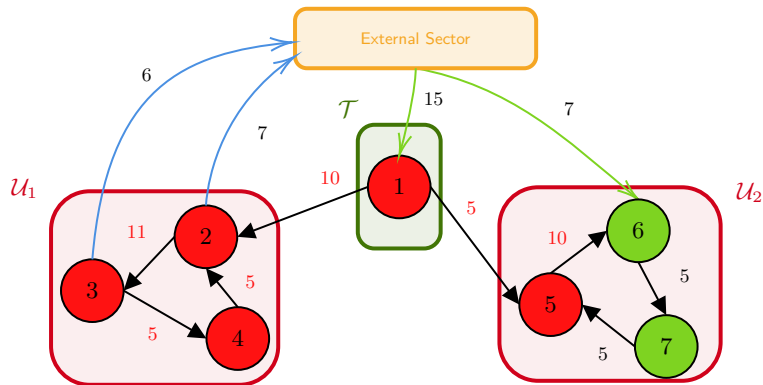


Example

$t = 5$



$$\begin{cases} x(t+1) = S_0^w (P^\top x(t) + c) \\ x(0) = w \end{cases}$$

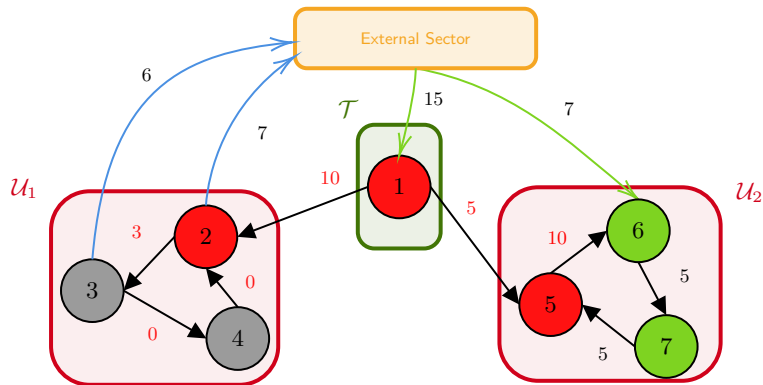


Example

$t = 14$



$$\begin{cases} x(t+1) &= S_0^w (P^\top x(t) + c) \\ x(0) &= w \end{cases}$$



Uniqueness of Clearing Vectors

Existence and uniqueness of equilibria

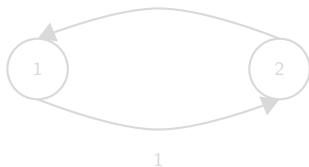


- Existence of equilibria follows from Brouwer fixed point Theorem.

In general however the equilibrium will not be unique:

Example

Consider the network described by $P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, $w = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $c = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.



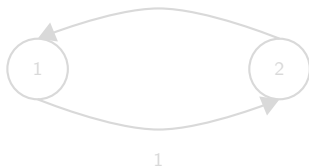
It is immediate to check that any $x = \begin{bmatrix} t \\ t \end{bmatrix}$, $t \in [0, 1]$ is an equilibrium.

- Existence of equilibria follows from Brouwer fixed point Theorem.

In general however the equilibrium will not be unique:

Example

Consider the network described by $P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, $w = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $c = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.



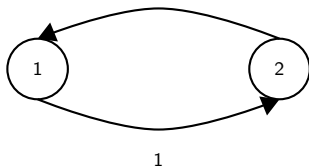
It is immediate to check that any $x = \begin{bmatrix} t \\ t \end{bmatrix}$, $t \in [0, 1]$ is an equilibrium.

- Existence of equilibria follows from Brouwer fixed point Theorem.

In general however the equilibrium will not be unique:

Example

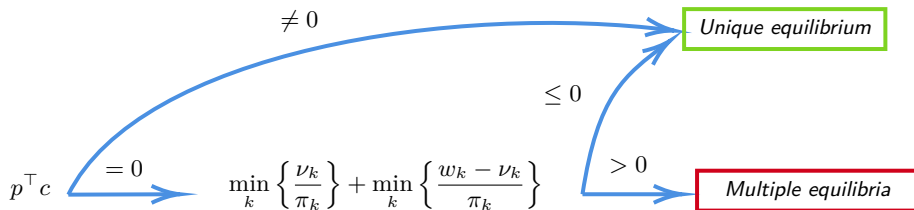
Consider the network described by $P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, $w = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $c = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.



It is immediate to check that any $x = \begin{bmatrix} t \\ t \end{bmatrix}$, $t \in [0, 1]$ is an equilibrium.

Theorem (Uniqueness for the irreducible case (Massai, Como, Fagnani, 2021))

Let (P, w) be a network such that P is irreducible and $\rho(P) = 1$. Let π and p be, respectively, left and right dominant eigenvectors of P . Let ν be any solution of $\nu = P^\top \nu + c$. Then it holds:

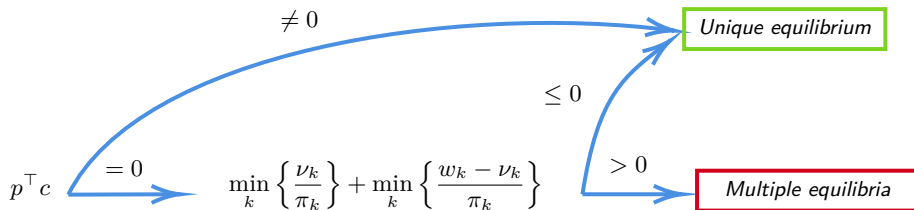


- In case we have multiple equilibria, the set of equilibria \mathcal{X} is:

$$\mathcal{X} = \left\{ x = \nu + \alpha \pi : - \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} \leq \alpha \leq \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} \right\}$$

Theorem (Uniqueness for the irreducible case (Massai, Como, Fagnani, 2021))

Let (P, w) be a network such that P is irreducible and $\rho(P) = 1$. Let π and p be, respectively, left and right dominant eigenvectors of P . Let ν be any solution of $\nu = P^\top \nu + c$. Then it holds:

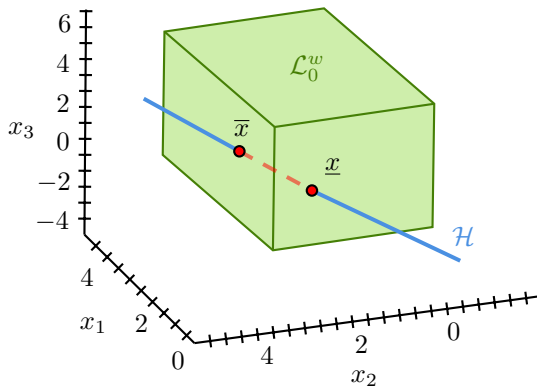


- In case we have multiple equilibria, the set of equilibria \mathcal{X} is:

$$\mathcal{X} = \left\{ x = \nu + \alpha \pi : - \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} \leq \alpha \leq \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} \right\}$$

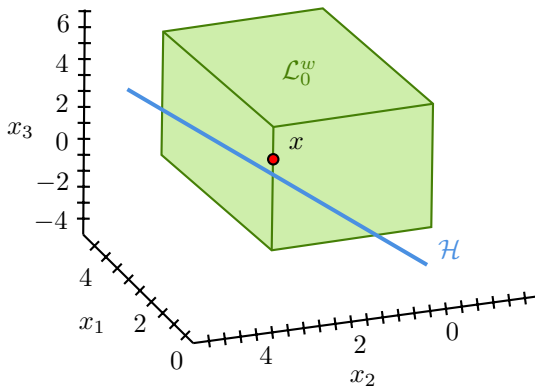
A geometrical interpretation

When $p^\top c = 0$, we have multiple equilibria when the line $\mathcal{H} = \{x \in \mathbb{R}^n : x = \nu + \alpha\pi, \alpha \in \mathbb{R}\}$ intersects non trivially the lattice \mathcal{L}_0^w .



(a) Multiple equilibria (the red dots and segment).

$$\min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} > 0$$



(b) Unique equilibrium (the red dot).

$$\min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} \leq 0$$

Continuity of network equilibria and the lack thereof

The dependence of equilibria on the flow



- Uniqueness ultimately depends on exogenous flow c .
- There exists a set \mathcal{M} of critical vectors c^* such that we have multiple solutions, namely:

$$\mathcal{U} = \{c \in \mathbb{R}^n : |\mathcal{X}(c)| = 1\}, \quad \mathcal{M} = \mathbb{R}^n \setminus \mathcal{U}$$

Theorem (Continuity of network equilibria (Massai, Como, Fagnani, 2021))

For a network (P, w) such that $\rho(P) \leq 1$, let m be number of basic classes of P . Then,

- (i) the non-uniqueness set \mathcal{M} has Lebesgue measure 0 and is contained in the closed set consisting of the union of at most m graphs of scalar continuous functions;
- (ii) the map $c \mapsto x(c)$ is continuous on the uniqueness set \mathcal{U} ;
- (iii) for every exogenous flow c^* in \mathcal{M} ,

$$\liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} x(c) = \underline{x}(c^*), \quad \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} x(c) = \bar{x}(c^*)$$

- For networks such that $\rho(P) = 1$ the equilibrium is generically unique.
- $x(c)$ is piece-wise continuous (and monotone) with jump discontinuities occurring exactly when crossing \mathcal{M} .

Continuity of network equilibria and the lack thereof

The dependence of equilibria on the flow



- Uniqueness ultimately depends on exogenous flow c .
- There exists a set \mathcal{M} of critical vectors c^* such that we have multiple solutions, namely:

$$\mathcal{U} = \{c \in \mathbb{R}^n : |\mathcal{X}(c)| = 1\}, \quad \mathcal{M} = \mathbb{R}^n \setminus \mathcal{U}$$

Theorem (Continuity of network equilibria (Massai, Como, Fagnani, 2021))

For a network (P, w) such that $\rho(P) \leq 1$, let m be number of basic classes of P . Then,

- (i) the non-uniqueness set \mathcal{M} has Lebesgue measure 0 and is contained in the closed set consisting of the union of at most m graphs of scalar continuous functions;
- (ii) the map $c \mapsto x(c)$ is continuous on the uniqueness set \mathcal{U} ;
- (iii) for every exogenous flow c^* in \mathcal{M} ,

$$\liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} x(c) = \underline{x}(c^*), \quad \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} x(c) = \bar{x}(c^*)$$

- For networks such that $\rho(P) = 1$ the equilibrium is generically unique.
- $x(c)$ is piece-wise continuous (and monotone) with jump discontinuities occurring exactly when crossing \mathcal{M} .

Continuity of network equilibria and the lack thereof

The dependence of equilibria on the flow



- Uniqueness ultimately depends on exogenous flow c .
- There exists a set \mathcal{M} of critical vectors c^* such that we have multiple solutions, namely:

$$\mathcal{U} = \{c \in \mathbb{R}^n : |\mathcal{X}(c)| = 1\}, \quad \mathcal{M} = \mathbb{R}^n \setminus \mathcal{U}$$

Theorem (Continuity of network equilibria (Massai, Como, Fagnani, 2021))

For a network (P, w) such that $\rho(P) \leq 1$, let m be number of basic classes of P . Then,

- (i) the non-uniqueness set \mathcal{M} has Lebesgue measure 0 and is contained in the closed set consisting of the union of at most m graphs of scalar continuous functions;
- (ii) the map $c \mapsto x(c)$ is continuous on the uniqueness set \mathcal{U} ;
- (iii) for every exogenous flow c^* in \mathcal{M} ,

$$\liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} x(c) = \underline{x}(c^*), \quad \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} x(c) = \bar{x}(c^*)$$

- For networks such that $\rho(P) = 1$ the equilibrium is generically unique.
- $x(c)$ is piece-wise continuous (and monotone) with jump discontinuities occurring exactly when crossing \mathcal{M} .

Jump discontinuity \implies slight change of c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Take an asset c° such that the system is healthy ($x(c^\circ) = w$) and another $c < c^\circ$ after a shock;
- Net worth before the shock: $v^\circ = P^\top w + c^\circ - w$;
- Net worth after the shock: $v = P^\top x(c) + c - w$;
- The loss is the aggregated difference between v° and v :

$$l(c^\circ, c) := \mathbf{1}^\top (v^\circ - v) = \mathbf{1}^\top (P^\top w + c^\circ - w - (P^\top x(c) + c - w)) = \underbrace{\mathbf{1}^\top (c^\circ - c)}_{\text{direct loss}} + \underbrace{\mathbf{1}^\top (w - x(c))}_{\text{shortfall term}}$$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) := \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) - \liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) = \|\bar{x}(c^*) - \underline{x}(c^*)\|_1.$$

Jump discontinuity \implies slight change of c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Take an asset c° such that the system is healthy ($x(c^\circ) = w$) and another $c < c^\circ$ after a shock;
- Net worth before the shock: $v^\circ = P^\top w + c^\circ - w$;
- Net worth after the shock: $v = P^\top x(c) + c - w$;
- The loss is the aggregated difference between v° and v :

$$l(c^\circ, c) := \mathbf{1}^\top (v^\circ - v) = \mathbf{1}^\top (P^\top w + c^\circ - w - (P^\top x(c) + c - w)) = \underbrace{\mathbf{1}^\top (c^\circ - c)}_{\text{direct loss}} + \underbrace{\mathbf{1}^\top (w - x(c))}_{\text{shortfall term}}$$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) := \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) - \liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) = \|\bar{x}(c^*) - \underline{x}(c^*)\|_1.$$

Jump discontinuity \implies slight change of c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Take an asset c° such that the system is healthy ($x(c^\circ) = w$) and another $c < c^\circ$ after a shock;
- Net worth before the shock: $v^\circ = P^\top w + c^\circ - w$;
- Net worth after the shock: $v = P^\top x(c) + c - w$;
- The loss is the aggregated difference between v° and v :

$$l(c^\circ, c) := \mathbf{1}^\top (v^\circ - v) = \mathbf{1}^\top (P^\top w + c^\circ - w - (P^\top x(c) + c - w)) = \underbrace{\mathbf{1}^\top (c^\circ - c)}_{\text{direct loss}} + \underbrace{\mathbf{1}^\top (w - x(c))}_{\text{shortfall term}}$$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) := \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) - \liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) = \|\bar{x}(c^*) - \underline{x}(c^*)\|_1.$$

Jump discontinuity \implies slight change of c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Take an asset c° such that the system is healthy ($x(c^\circ) = w$) and another $c < c^\circ$ after a shock;
- Net worth before the shock: $v^\circ = P^\top w + c^\circ - w$;
- Net worth after the shock: $v = P^\top x(c) + c - w$;
- The loss is the aggregated difference between v° and v :

$$l(c^\circ, c) := \mathbf{1}^\top (v^\circ - v) = \mathbf{1}^\top (P^\top w + c^\circ - w - (P^\top x(c) + c - w)) = \underbrace{\mathbf{1}^\top (c^\circ - c)}_{\text{direct loss}} + \underbrace{\mathbf{1}^\top (w - x(c))}_{\text{shortfall term}}$$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) := \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) - \liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) = \|\bar{x}(c^*) - \underline{x}(c^*)\|_1.$$

Jump discontinuity \implies slight change of c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Take an asset c° such that the system is healthy ($x(c^\circ) = w$) and another $c < c^\circ$ after a shock;
- Net worth before the shock: $v^\circ = P^\top w + c^\circ - w$;
- Net worth after the shock: $v = P^\top x(c) + c - w$;
- The loss is the aggregated difference between v° and v :

$$l(c^\circ, c) := \mathbf{1}^\top (v^\circ - v) = \mathbf{1}^\top (P^\top w + c^\circ - w - (P^\top x(c) + c - w)) = \underbrace{\mathbf{1}^\top (c^\circ - c)}_{\text{direct loss}} + \underbrace{\mathbf{1}^\top (w - x(c))}_{\text{shortfall term}}$$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) := \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) - \liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) = \|\bar{x}(c^*) - \underline{x}(c^*)\|_1.$$



Jump discontinuity \implies slight change of c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Take an asset c° such that the system is healthy ($x(c^\circ) = w$) and another $c < c^\circ$ after a shock;
- Net worth before the shock: $v^\circ = P^\top w + c^\circ - w$;
- Net worth after the shock: $v = P^\top x(c) + c - w$;
- The loss is the aggregated difference between v° and v :

$$l(c^\circ, c) := \mathbf{1}^\top (v^\circ - v) = \mathbf{1}^\top (P^\top w + c^\circ - w - (P^\top x(c) + c - w)) = \underbrace{\mathbf{1}^\top (c^\circ - c)}_{\text{direct loss}} + \underbrace{\mathbf{1}^\top (w - x(c))}_{\text{shortfall term}}$$

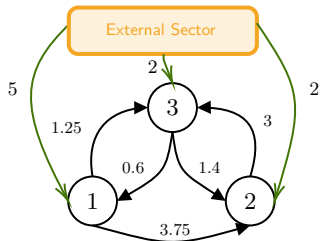
Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) := \limsup_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) - \liminf_{\substack{c \in \mathcal{U} \\ c \rightarrow c^*}} l(c^\circ, c) = \|\bar{x}(c^*) - \underline{x}(c^*)\|_1.$$

Example

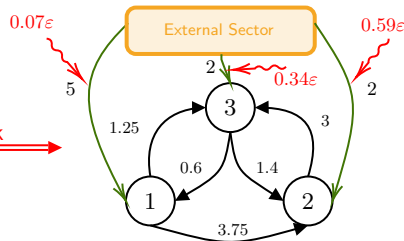
- Consider a network with $P = \begin{bmatrix} 0 & 0.75 & 0.25 \\ 0 & 0 & 1 \\ 0.3 & 0.7 & 0 \end{bmatrix}$ and $w = \begin{bmatrix} 5 \\ 3 \\ 2 \end{bmatrix}$.
- Consider an initial vector $c^\circ = [5, 2, 2]^\top$ that we perturb with a shock ε such that:

$$c = c^\circ - \varepsilon v, \quad v = \begin{bmatrix} 0.07 \\ 0.59 \\ 0.34 \end{bmatrix}, \quad \varepsilon \in [0, 14]$$



$$c^\circ = [5, 2, 2]^\top$$

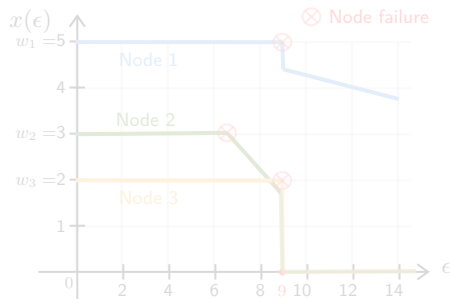
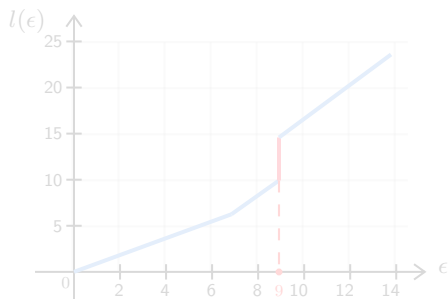
Shock \Rightarrow



$$c = c^\circ - \varepsilon [0.07, 0.59, 0.34]^\top$$

Example

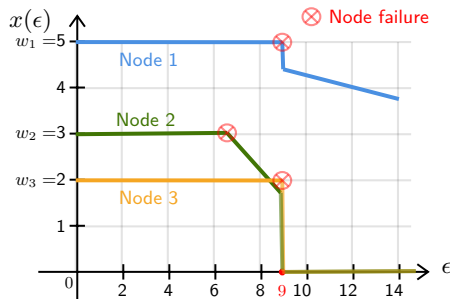
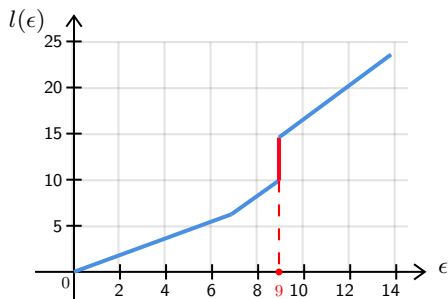
- We expect a jump discontinuity when $\mathbf{1}^\top c = 0 \implies \varepsilon = 9 \implies c^* = [4.4, -3.3, -1.1]^\top$.



- The size of the jump is $\Delta l(c^*) = \min_i \left\{ \frac{\nu_i}{\pi_i} \right\} + \min_i \left\{ \frac{w_i - \nu_i}{\pi_i} \right\} \approx 4.44$
- At c^* the network suffers a dramatic crisis as node 1 and 3 suddenly default.
- Node 3 goes from fully solvent ($x_3 = w_3$) to completely insolvent ($x_3 = 0$).

Example

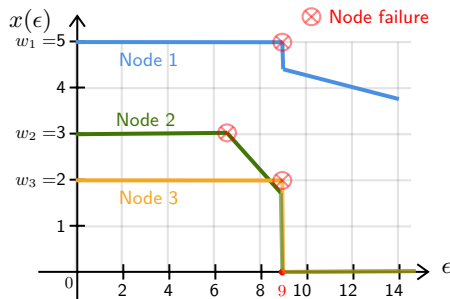
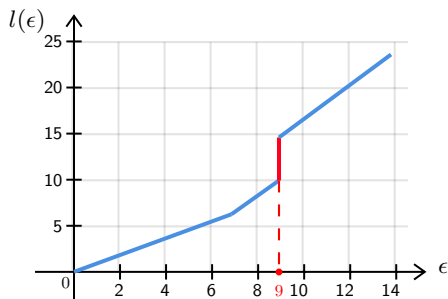
- We expect a jump discontinuity when $\mathbf{1}^\top c = 0 \implies \varepsilon = 9 \implies c^* = [4.4, -3.3, -1.1]^\top$.



- The size of the jump is $\Delta l(c^*) = \min_i \left\{ \frac{\nu_i}{\pi_i} \right\} + \min_i \left\{ \frac{w_i - \nu_i}{\pi_i} \right\} \approx 4.44$
- At c^* the network suffers a dramatic crisis as node 1 and 3 suddenly default.
- Node 3 goes from fully solvent ($x_3 = w_3$) to completely insolvent ($x_3 = 0$).

Example

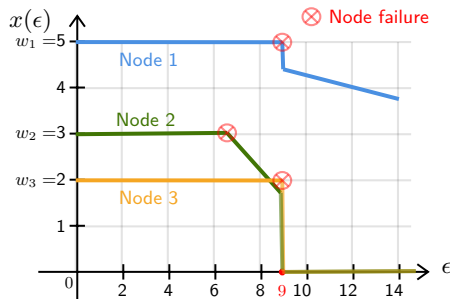
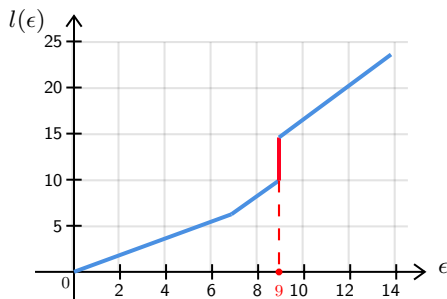
- We expect a jump discontinuity when $\mathbf{1}^\top c = 0 \implies \varepsilon = 9 \implies c^* = [4.4, -3.3, -1.1]^\top$.



- The size of the jump is $\Delta l(c^*) = \min_i \left\{ \frac{\nu_i}{\pi_i} \right\} + \min_i \left\{ \frac{w_i - \nu_i}{\pi_i} \right\} \approx 4.44$
- At c^* the network suffers a dramatic crisis as node 1 and 3 suddenly default.
- Node 3 goes from fully solvent ($x_3 = w_3$) to completely insolvent ($x_3 = 0$).

Example

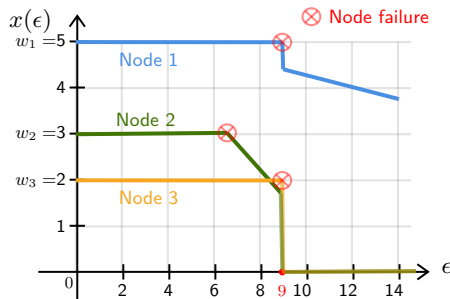
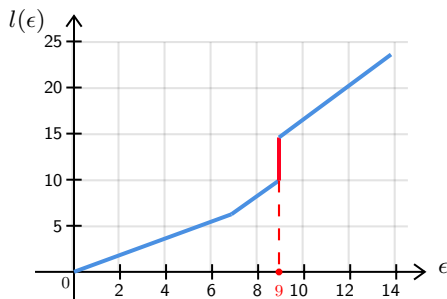
- We expect a jump discontinuity when $\mathbf{1}^\top c = 0 \implies \varepsilon = 9 \implies c^* = [4.4, -3.3, -1.1]^\top$.



- The size of the jump is $\Delta l(c^*) = \min_i \left\{ \frac{\nu_i}{\pi_i} \right\} + \min_i \left\{ \frac{w_i - \nu_i}{\pi_i} \right\} \approx 4.44$
- At c^* the network suffers a dramatic crisis as node 1 and 3 suddenly default.
- Node 3 goes from fully solvent ($x_3 = w_3$) to completely insolvent ($x_3 = 0$).

Example

- We expect a jump discontinuity when $\mathbf{1}^\top c = 0 \implies \varepsilon = 9 \implies c^* = [4.4, -3.3, -1.1]^\top$.



- The size of the jump is $\Delta l(c^*) = \min_i \left\{ \frac{\nu_i}{\pi_i} \right\} + \min_i \left\{ \frac{w_i - \nu_i}{\pi_i} \right\} \approx 4.44$
- At c^* the network suffers a dramatic crisis as node 1 and 3 suddenly default.
- Node 3 goes from fully solvent ($x_3 = w_3$) to completely insolvent ($x_3 = 0$).

- $P^{(\delta)} = \delta G$ where G is some fixed matrix and $\delta > 0$ describes the strength of interactions among players.
- If we put $\delta^* = \rho(G)^{-1}$, we have that $\rho(\delta G) < 1$ for $\delta < \delta^*$.
- The sensitivity of the unique Nash equilibrium to the variation of c may grow unbounded when δ approaches δ^* if the limit network admits multiple equilibria.

Proposition (Sensitivity of Nash equilibria (Massai, Como, Fagnani, 2021))

Let $P^{(\delta)} = \delta G$ with G irreducible, $\delta \in (0, \delta^*]$ and let $\bar{x}^{(\delta)}(c)$ and $\underline{x}^{(\delta)}(c)$ to be the min. and max. equilibria of $(P^{(\delta)}, w)$ with $c \in \mathbb{R}^n$. Write $x^{(\delta)}$ for the equilibrium when it is unique. Let c^* be such that the (P^{δ^*}, w) has multiple network equilibria. Then,

$$\sup_{\delta < \delta^*} \sup_{c: \|c - c^*\| \leq \epsilon} \|x^{(\delta)}(c) - x^{(\delta)}(c^*)\| \geq \|\bar{x}^{(\delta^*)}(c^*) - \underline{x}^{(\delta^*)}(c^*)\| > 0,$$

for every monotone norm $\|\cdot\|$ and every $\epsilon > 0$.

- Arbitrarily small variations in the exogenous flow c will determine, for δ close to δ^* , a variation in the equilibrium of the size of the set of equilibria for the limit case $\delta = \delta^*$.

- $P^{(\delta)} = \delta G$ where G is some fixed matrix and $\delta > 0$ describes the strength of interactions among players.
- If we put $\delta^* = \rho(G)^{-1}$, we have that $\rho(\delta G) < 1$ for $\delta < \delta^*$.
- The sensitivity of the unique Nash equilibrium to the variation of c may grow unbounded when δ approaches δ^* if the limit network admits multiple equilibria.

Proposition (Sensitivity of Nash equilibria (Massai, Como, Fagnani, 2021))

Let $P^{(\delta)} = \delta G$ with G irreducible, $\delta \in (0, \delta^*]$ and let $\bar{x}^{(\delta)}(c)$ and $\underline{x}^{(\delta)}(c)$ to be the min. and max. equilibria of $(P^{(\delta)}, w)$ with $c \in \mathbb{R}^n$. Write $x^{(\delta)}$ for the equilibrium when it is unique. Let c^* be such that the (P^{δ^*}, w) has multiple network equilibria. Then,

$$\sup_{\delta < \delta^*} \sup_{c: \|c - c^*\| \leq \epsilon} \|x^{(\delta)}(c) - x^{(\delta)}(c^*)\| \geq \|\bar{x}^{(\delta^*)}(c^*) - \underline{x}^{(\delta^*)}(c^*)\| > 0,$$

for every monotone norm $\|\cdot\|$ and every $\epsilon > 0$.

- Arbitrarily small variations in the exogenous flow c will determine, for δ close to δ^* , a variation in the equilibrium of the size of the set of equilibria for the limit case $\delta = \delta^*$.

- $P^{(\delta)} = \delta G$ where G is some fixed matrix and $\delta > 0$ describes the strength of interactions among players.
- If we put $\delta^* = \rho(G)^{-1}$, we have that $\rho(\delta G) < 1$ for $\delta < \delta^*$.
- The sensitivity of the unique Nash equilibrium to the variation of c may grow unbounded when δ approaches δ^* if the limit network admits multiple equilibria.

Proposition (Sensitivity of Nash equilibria (Massai, Como, Fagnani, 2021))

Let $P^{(\delta)} = \delta G$ with G irreducible, $\delta \in (0, \delta^*]$ and let $\bar{x}^{(\delta)}(c)$ and $\underline{x}^{(\delta)}(c)$ to be the min. and max. equilibria of $(P^{(\delta)}, w)$ with $c \in \mathbb{R}^n$. Write $x^{(\delta)}$ for the equilibrium when it is unique. Let c^* be such that the (P^{δ^*}, w) has multiple network equilibria. Then,

$$\sup_{\delta < \delta^*} \sup_{c: \|c - c^*\| \leq \epsilon} \|x^{(\delta)}(c) - x^{(\delta)}(c^*)\| \geq \|\bar{x}^{(\delta^*)}(c^*) - \underline{x}^{(\delta^*)}(c^*)\| > 0,$$

for every monotone norm $\|\cdot\|$ and every $\epsilon > 0$.

- Arbitrarily small variations in the exogenous flow c will determine, for δ close to δ^* , a variation in the equilibrium of the size of the set of equilibria for the limit case $\delta = \delta^*$.

- $P^{(\delta)} = \delta G$ where G is some fixed matrix and $\delta > 0$ describes the strength of interactions among players.
- If we put $\delta^* = \rho(G)^{-1}$, we have that $\rho(\delta G) < 1$ for $\delta < \delta^*$.
- The sensitivity of the unique Nash equilibrium to the variation of c may grow unbounded when δ approaches δ^* if the limit network admits multiple equilibria.

Proposition (Sensitivity of Nash equilibria (Massai, Como, Fagnani, 2021))

Let $P^{(\delta)} = \delta G$ with G irreducible, $\delta \in (0, \delta^*]$ and let $\bar{x}^{(\delta)}(c)$ and $\underline{x}^{(\delta)}(c)$ to be the min. and max. equilibria of $(P^{(\delta)}, w)$ with $c \in \mathbb{R}^n$. Write $x^{(\delta)}$ for the equilibrium when it is unique. Let c^* be such that the (P^{δ^*}, w) has multiple network equilibria. Then,

$$\sup_{\delta < \delta^*} \sup_{c: \|c - c^*\| \leq \epsilon} \|x^{(\delta)}(c) - x^{(\delta)}(c^*)\| \geq \|\bar{x}^{(\delta^*)}(c^*) - \underline{x}^{(\delta^*)}(c^*)\| > 0,$$

for every monotone norm $\|\cdot\|$ and every $\epsilon > 0$.

- Arbitrarily small variations in the exogenous flow c will determine, for δ close to δ^* , a variation in the equilibrium of the size of the set of equilibria for the limit case $\delta = \delta^*$.

- $P^{(\delta)} = \delta G$ where G is some fixed matrix and $\delta > 0$ describes the strength of interactions among players.
- If we put $\delta^* = \rho(G)^{-1}$, we have that $\rho(\delta G) < 1$ for $\delta < \delta^*$.
- The sensitivity of the unique Nash equilibrium to the variation of c may grow unbounded when δ approaches δ^* if the limit network admits multiple equilibria.

Proposition (Sensitivity of Nash equilibria (Massai, Como, Fagnani, 2021))

Let $P^{(\delta)} = \delta G$ with G irreducible, $\delta \in (0, \delta^*]$ and let $\bar{x}^{(\delta)}(c)$ and $\underline{x}^{(\delta)}(c)$ to be the min. and max. equilibria of $(P^{(\delta)}, w)$ with $c \in \mathbb{R}^n$. Write $x^{(\delta)}$ for the equilibrium when it is unique. Let c^* be such that the (P^{δ^*}, w) has multiple network equilibria. Then,

$$\sup_{\delta < \delta^* c: \|c - c^*\| \leq \epsilon} \|x^{(\delta)}(c) - x^{(\delta)}(c^*)\| \geq \|\bar{x}^{(\delta^*)}(c^*) - \underline{x}^{(\delta^*)}(c^*)\| > 0,$$

for every monotone norm $\|\cdot\|$ and every $\epsilon > 0$.

- Arbitrarily small variations in the exogenous flow c will determine, for δ close to δ^* , a variation in the equilibrium of the size of the set of equilibria for the limit case $\delta = \delta^*$.

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).

Main results

- Sufficient and necessary condition for uniqueness of network equilibria;
- structure of solutions with respect to the network's properties;
- discontinuity jumps of equilibria and implications for systemic risk;
- global stability and convergence of equilibria in a dynamical setting.

Ongoing research

- Analytical results on particular topologies and random graphs;
- risk-based centrality measures;
- model extensions (fire sales, bankruptcy costs, cross holdings, etc...).



Thank you for your attention!

A Fundamental Partition

To every solution $x \in \mathcal{X}$, we attach a node partition: a node $i \in \mathcal{V}$ is called a



The Fundamental Partition

- $i \in \mathcal{V}_x^+$ *surplus node* if $c_i + \sum_{k \neq i} P_{ki} x_k > w_i \implies x_i = w_i$;
- $i \in \mathcal{V}_x^0$ *exposed node* if $0 \leq c_i + \sum_{k \neq i} P_{ki} x_k \leq w_i \implies x_i = c_i + \sum_{k \neq i} P_{ki} x_k$;
- $i \in \mathcal{V}_x^-$ *deficit node* if $c_i + \sum_{k \neq i} P_{ki} x_k < 0 \implies x_i = 0$.

Theorem (Invariance of the Fundamental Partition)

The partition $\mathcal{V}_x^-, \mathcal{V}_x^+, \mathcal{V}_x^0$ is invariant over all solutions $x \in \mathcal{X}$.

The unique partition of nodes can be denoted with the triple $\mathcal{V}^+, \mathcal{V}^0, \mathcal{V}^-$. For every x we have:

$$x = \begin{bmatrix} x_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ x_{\mathcal{V}^-} \end{bmatrix} = \begin{bmatrix} w_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ 0 \end{bmatrix}$$

- What remains to be studied is the structure of the solutions on \mathcal{V}^0 .
- Notice that $x_{\mathcal{V}^0} = S_0^w (P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}) = P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}$; a linear equation!

A Fundamental Partition



To every solution $x \in \mathcal{X}$, we attach a node partition: a node $i \in \mathcal{V}$ is called a

The Fundamental Partition

- $i \in \mathcal{V}_x^+$ *surplus node* if $c_i + \sum_{k \neq i} P_{ki} x_k > w_i \implies x_i = w_i$;
- $i \in \mathcal{V}_x^0$ *exposed node* if $0 \leq c_i + \sum_{k \neq i} P_{ki} x_k \leq w_i \implies x_i = c_i + \sum_{k \neq i} P_{ki} x_k$;
- $i \in \mathcal{V}_x^-$ *deficit node* if $c_i + \sum_{k \neq i} P_{ki} x_k < 0 \implies x_i = 0$.

Theorem (Invariance of the Fundamental Partition)

The partition $\mathcal{V}_x^-, \mathcal{V}_x^+, \mathcal{V}_x^0$ is invariant over all solutions $x \in \mathcal{X}$.

The unique partition of nodes can be denoted with the triple $\mathcal{V}^+, \mathcal{V}^0, \mathcal{V}^-$. For every x we have:

$$x = \begin{bmatrix} x_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ x_{\mathcal{V}^-} \end{bmatrix} = \begin{bmatrix} w_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ 0 \end{bmatrix}$$

- What remains to be studied is the structure of the solutions on \mathcal{V}^0 .
- Notice that $x_{\mathcal{V}^0} = S_0^w (P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}) = P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}$; a linear equation!

A Fundamental Partition



To every solution $x \in \mathcal{X}$, we attach a node partition: a node $i \in \mathcal{V}$ is called a

The Fundamental Partition

- $i \in \mathcal{V}_x^+$ *surplus node* if $c_i + \sum_{k \neq i} P_{ki} x_k > w_i \implies x_i = w_i$;
- $i \in \mathcal{V}_x^0$ *exposed node* if $0 \leq c_i + \sum_{k \neq i} P_{ki} x_k \leq w_i \implies x_i = c_i + \sum_{k \neq i} P_{ki} x_k$;
- $i \in \mathcal{V}_x^-$ *deficit node* if $c_i + \sum_{k \neq i} P_{ki} x_k < 0 \implies x_i = 0$.

Theorem (Invariance of the Fundamental Partition)

The partition $\mathcal{V}_x^-, \mathcal{V}_x^+, \mathcal{V}_x^0$ is invariant over all solutions $x \in \mathcal{X}$.

The unique partition of nodes can be denoted with the triple $\mathcal{V}^+, \mathcal{V}^0, \mathcal{V}^-$. For every x we have:

$$x = \begin{bmatrix} x_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ x_{\mathcal{V}^-} \end{bmatrix} = \begin{bmatrix} w_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ 0 \end{bmatrix}$$

- What remains to be studied is the structure of the solutions on \mathcal{V}^0 .
- Notice that $x_{\mathcal{V}^0} = S_0^w (P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}) = P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}$; a linear equation!

A Fundamental Partition



To every solution $x \in \mathcal{X}$, we attach a node partition: a node $i \in \mathcal{V}$ is called a

The Fundamental Partition

- $i \in \mathcal{V}_x^+$ *surplus node* if $c_i + \sum_{k \neq i} P_{ki} x_k > w_i \implies x_i = w_i$;
- $i \in \mathcal{V}_x^0$ *exposed node* if $0 \leq c_i + \sum_{k \neq i} P_{ki} x_k \leq w_i \implies x_i = c_i + \sum_{k \neq i} P_{ki} x_k$;
- $i \in \mathcal{V}_x^-$ *deficit node* if $c_i + \sum_{k \neq i} P_{ki} x_k < 0 \implies x_i = 0$.

Theorem (Invariance of the Fundamental Partition)

The partition $\mathcal{V}_x^-, \mathcal{V}_x^+, \mathcal{V}_x^0$ is invariant over all solutions $x \in \mathcal{X}$.

The unique partition of nodes can be denoted with the triple $\mathcal{V}^+, \mathcal{V}^0, \mathcal{V}^-$. For every x we have:

$$x = \begin{bmatrix} x_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ x_{\mathcal{V}^-} \end{bmatrix} = \begin{bmatrix} w_{\mathcal{V}^+} \\ x_{\mathcal{V}^0} \\ 0 \end{bmatrix}$$

- What remains to be studied is the structure of the solutions on \mathcal{V}^0 .
- Notice that $x_{\mathcal{V}^0} = \mathcal{S}_0^w(P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}) = P'_{\mathcal{V}^0} x_{\mathcal{V}^0} + c_{\mathcal{V}^0}$; a linear equation!

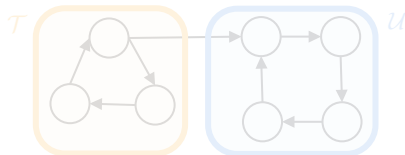
Theorem (Uniqueness for out-connected graphs)

Let P be an out-connected matrix, then the clearing vector is unique.

Proof.

By the invariance of the partition, we just need to check uniqueness for nodes in \mathcal{V}_0 . We have $x_{\mathcal{V}_0} = P'_{\mathcal{V}_0} x_{\mathcal{V}_0} + c_{\mathcal{V}_0} \implies x_{\mathcal{V}_0} = (I - P'_{\mathcal{V}_0})^{-1} c_{\mathcal{V}_0}$ and hence the solution is unique. Notice that $(I - P'_{\mathcal{V}_0})$ is invertible since $P_{\mathcal{V}_0}$ is an out-connected matrix. \square

- We can partition any graph in a transient part \mathcal{T} and trapping sets \mathcal{U} . I.e. $\mathcal{V} = \mathcal{T} \cup (\cup_k \mathcal{U}_k)$;
- $P_{\mathcal{T}}$ is out-connected \implies the solution $x_{\mathcal{T}}$ is unique.



- What about the solution on \mathcal{U} ? Notice that $P_{\mathcal{U}}$ is stochastic and irreducible.

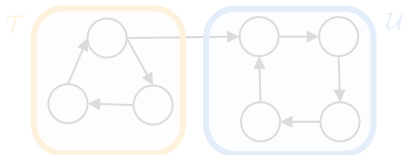
Theorem (Uniqueness for out-connected graphs)

Let P be an out-connected matrix, then the clearing vector is unique.

Proof.

By the invariance of the partition, we just need to check uniqueness for nodes in \mathcal{V}_0 . We have $x_{\mathcal{V}_0} = P'_{\mathcal{V}_0} x_{\mathcal{V}_0} + c_{\mathcal{V}_0} \implies x_{\mathcal{V}_0} = (I - P'_{\mathcal{V}_0})^{-1} c_{\mathcal{V}_0}$ and hence the solution is unique. Notice that $(I - P'_{\mathcal{V}_0})$ is invertible since $P_{\mathcal{V}_0}$ is an out-connected matrix. \square

- We can partition any graph in a transient part \mathcal{T} and trapping sets \mathcal{U} . I.e. $\mathcal{V} = \mathcal{T} \cup (\cup_k \mathcal{U}_k)$;
- $P_{\mathcal{T}}$ is out-connected \implies the solution $x_{\mathcal{T}}$ is unique.



- What about the solution on \mathcal{U} ? Notice that $P_{\mathcal{U}}$ is stochastic and irreducible.

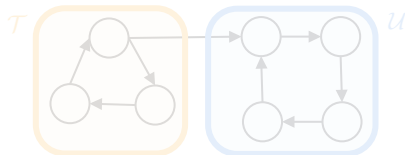
Theorem (Uniqueness for out-connected graphs)

Let P be an out-connected matrix, then the clearing vector is unique.

Proof.

By the invariance of the partition, we just need to check uniqueness for nodes in \mathcal{V}_0 . We have $x_{\mathcal{V}_0} = P'_{\mathcal{V}_0} x_{\mathcal{V}_0} + c_{\mathcal{V}_0} \implies x_{\mathcal{V}_0} = (I - P'_{\mathcal{V}_0})^{-1} c_{\mathcal{V}_0}$ and hence the solution is unique. Notice that $(I - P'_{\mathcal{V}_0})$ is invertible since $P_{\mathcal{V}_0}$ is an out-connected matrix. \square

- We can partition any graph in a transient part \mathcal{T} and trapping sets \mathcal{U} . I.e. $\mathcal{V} = \mathcal{T} \cup (\cup_k \mathcal{U}_k)$;
- $P_{\mathcal{T}}$ is out-connected \implies the solution $x_{\mathcal{T}}$ is unique.



- What about the solution on \mathcal{U} ? Notice that $P_{\mathcal{U}}$ is stochastic and irreducible.

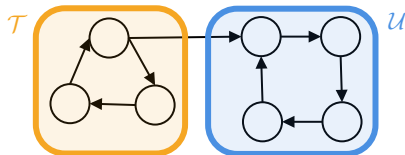
Theorem (Uniqueness for out-connected graphs)

Let P be an out-connected matrix, then the clearing vector is unique.

Proof.

By the invariance of the partition, we just need to check uniqueness for nodes in \mathcal{V}_0 . We have $x_{\mathcal{V}_0} = P'_{\mathcal{V}_0} x_{\mathcal{V}_0} + c_{\mathcal{V}_0} \implies x_{\mathcal{V}_0} = (I - P'_{\mathcal{V}_0})^{-1} c_{\mathcal{V}_0}$ and hence the solution is unique. Notice that $(I - P'_{\mathcal{V}_0})$ is invertible since $P_{\mathcal{V}_0}$ is an out-connected matrix. \square

- We can partition any graph in a transient part \mathcal{T} and trapping sets \mathcal{U} . I.e. $\mathcal{V} = \mathcal{T} \cup (\cup_k \mathcal{U}_k)$;
- $P_{\mathcal{T}}$ is out-connected \implies the solution $x_{\mathcal{T}}$ is unique.



- What about the solution on \mathcal{U} ? Notice that $P_{\mathcal{U}}$ is stochastic and irreducible.

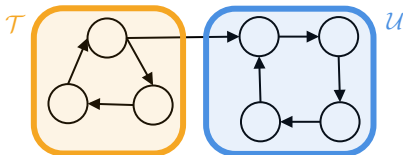
Theorem (Uniqueness for out-connected graphs)

Let P be an out-connected matrix, then the clearing vector is unique.

Proof.

By the invariance of the partition, we just need to check uniqueness for nodes in \mathcal{V}_0 . We have $x_{\mathcal{V}_0} = P'_{\mathcal{V}_0} x_{\mathcal{V}_0} + c_{\mathcal{V}_0} \implies x_{\mathcal{V}_0} = (I - P'_{\mathcal{V}_0})^{-1} c_{\mathcal{V}_0}$ and hence the solution is unique. Notice that $(I - P'_{\mathcal{V}_0})$ is invertible since $P_{\mathcal{V}_0}$ is an out-connected matrix. \square

- We can partition any graph in a transient part \mathcal{T} and trapping sets \mathcal{U} . I.e. $\mathcal{V} = \mathcal{T} \cup (\cup_k \mathcal{U}_k)$;
- $P_{\mathcal{T}}$ is out-connected \implies the solution $x_{\mathcal{T}}$ is unique.

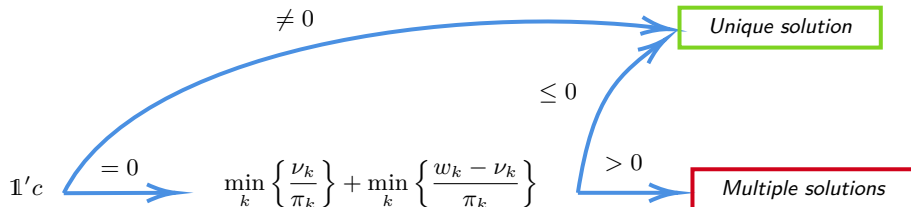


- What about the solution on \mathcal{U} ? Notice that $P_{\mathcal{U}}$ is stochastic and irreducible.

Theorem (Uniqueness for the stochastic irreducible case)

Let P be an irreducible stochastic matrix; let π be its unique invariant probability measure and

$$\nu = \frac{1}{2} \sum_{k \geq 0} \left(\frac{I + P^k}{2} \right) c. \text{ Then it holds:}$$



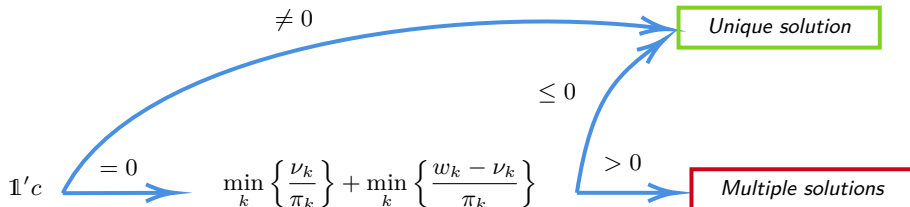
- In case we have multiple solutions, we have that:

$$\mathcal{X} = \left\{ x = \nu + \alpha \pi : - \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} \leq \alpha \leq \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} \right\}$$

Theorem (Uniqueness for the stochastic irreducible case)

Let P be an irreducible stochastic matrix; let π be its unique invariant probability measure and

$$\nu = \frac{1}{2} \sum_{k \geq 0} \left(\frac{I + P^k}{2} \right) c. \text{ Then it holds:}$$

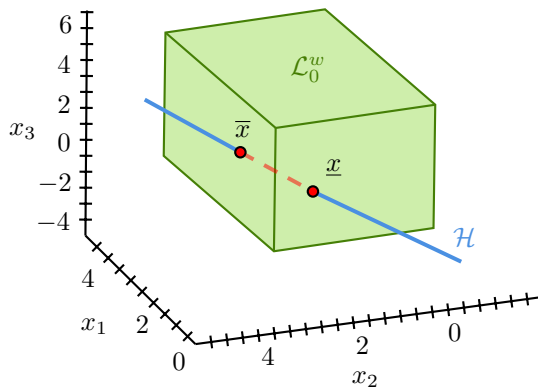


- In case we have multiple solutions, we have that:

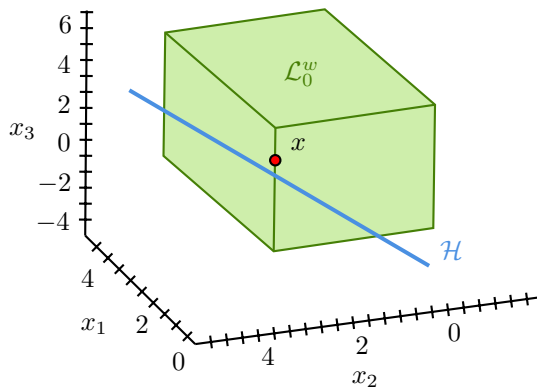
$$\mathcal{X} = \left\{ x = \nu + \alpha \pi : - \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} \leq \alpha \leq \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} \right\}$$

A geometrical Interpretation

When $\mathbb{1}'c = 0$, we have multiple solutions when the line $\mathcal{H} = \{x \in \mathbb{R}^n : x = \nu + \alpha\pi\}$ intersects non trivially the lattice \mathcal{L}_0^w . This corresponds to $\min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} > 0$



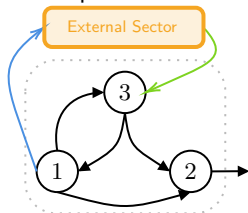
(m) Multiple solutions (the red dots and the red segment).



(n) Unique solution (the red dot).

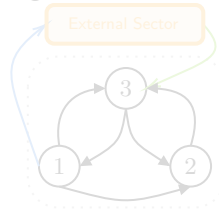
The Out-Connected Case

Unique solution.

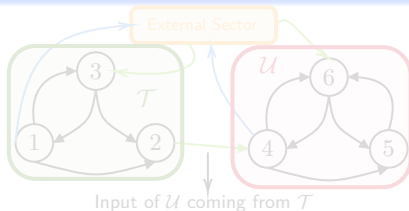


The Stochastic-Irreducible Case

Uniqueness depends on c , i.e. on what is coming from and going to the external environment.



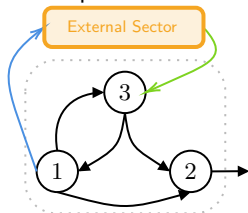
The General Case



- $x_{\mathcal{T}}$ is unique;
- For every trapping set \mathcal{U} , we use the Theorem;
- To do so, we also need to consider the input coming from \mathcal{T} : $h_{\mathcal{U}} := c_{\mathcal{U}} + P_{\mathcal{U}\mathcal{T}}x_{\mathcal{T}}$

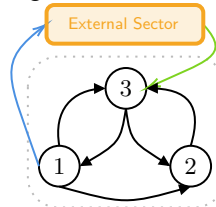
The Out-Connected Case

Unique solution.

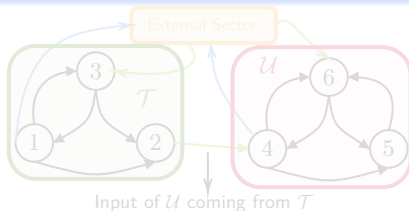


The Stochastic-Irreducible Case

Uniqueness depends on c , i.e. on what is coming from and going to the external environment.



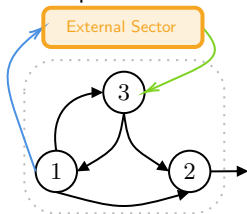
The General Case



- $x_{\mathcal{T}}$ is unique;
- For every trapping set \mathcal{U} , we use the Theorem;
- To do so, we also need to consider the input coming from \mathcal{T} : $h_{\mathcal{U}} := c_{\mathcal{U}} + P_{\mathcal{U}\mathcal{T}}x_{\mathcal{T}}$

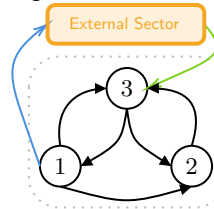
The Out-Connected Case

Unique solution.

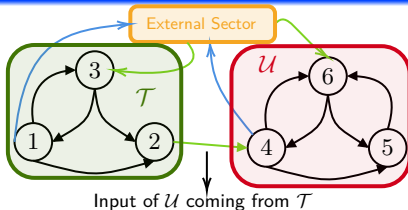


The Stochastic-Irreducible Case

Uniqueness depends on c , i.e. on what is coming from and going to the external environment.



The General Case



- $x_{\mathcal{T}}$ is unique;
- For every trapping set \mathcal{U} , we use the Theorem;
- To do so, we also need to consider the input coming from \mathcal{T} : $h_{\mathcal{U}} := c_{\mathcal{U}} + P_{\mathcal{U}\mathcal{T}}x_{\mathcal{T}}$

Dependence of x on c

- The uniqueness ultimately depends on the input \ output vector c .
- There exists a set of critical vectors c^* such that we have multiple solutions, namely:

$$\mathcal{M} = \left\{ c \in \mathbb{R}^n : \mathbf{1}'c = 0, \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} > 0 \right\}$$

What happens to the solutions when c approaches a critical $c^* \in \mathcal{M}$?

Let $\mathcal{A} = \mathbb{R}^n \setminus \mathcal{M}$ be the set where the solution is unique. Then:

- The map $c \mapsto x(c)$ is continuous on \mathcal{A} .
- One can prove that for every $c^* \in \mathcal{M}$,

$$\liminf_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} x(c) = \underline{x}(c^*), \quad \limsup_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} x(c) = \bar{x}(c^*).$$

- This means that the clearing vector undergoes a jump discontinuity at c^* .

Dependence of x on c

- The uniqueness ultimately depends on the input \ output vector c .
- There exists a set of critical vectors c^* such that we have multiple solutions, namely:

$$\mathcal{M} = \left\{ c \in \mathbb{R}^n : \mathbf{1}'c = 0, \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\} > 0 \right\}$$

What happens to the solutions when c approaches a critical $c^* \in \mathcal{M}$?

Let $\mathcal{A} = \mathbb{R}^n \setminus \mathcal{M}$ be the set where the solution is unique. Then:

- The map $c \mapsto x(c)$ is continuous on \mathcal{A} .
- One can prove that for every $c^* \in \mathcal{M}$,

$$\liminf_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} x(c) = \underline{x}(c^*), \quad \limsup_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} x(c) = \bar{x}(c^*).$$

- This means that the clearing vector undergoes a jump discontinuity at c^* .

Jump discontinuity as a financial breakdown

A jump discontinuity means that even a slight change in the asset/shock value c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Consider shock ε that lowers the value of the external asset from c to $c - \varepsilon$;
- Loss function is: $l = \mathbb{1}'(\varepsilon + w - x)$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) = \liminf_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) - \limsup_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) = \mathbb{1}'(\bar{x}(c^*) - \underline{x}(c^*)) = \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\}$$

Maximal norm of a jump discontinuity

$$\max_{c \in \mathbb{R}^n} \|\bar{x}(c) - \underline{x}(c)\|_p^p = \left(\min_k \frac{w_k}{\pi_k} \right)^p \|\pi\|_p^p$$

Jump discontinuity as a financial breakdown

A jump discontinuity means that even a slight change in the asset/shock value c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Consider shock ε that lowers the value of the external asset from c to $c - \varepsilon$;
- Loss function is: $l = \mathbb{1}'(\varepsilon + w - x)$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) = \liminf_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) - \limsup_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) = \mathbb{1}'(\bar{x}(c^*) - \underline{x}(c^*)) = \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\}$$

Maximal norm of a jump discontinuity

$$\max_{c \in \mathbb{R}^n} \|\bar{x}(c) - \underline{x}(c)\|_p^p = \left(\min_k \frac{w_k}{\pi_k} \right)^p \|\pi\|_p^p$$

Jump discontinuity as a financial breakdown

A jump discontinuity means that even a slight change in the asset/shock value c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Consider shock ε that lowers the value of the external asset from c to $c - \varepsilon$;
- Loss function is: $l = \mathbb{1}'(\varepsilon + w - x)$

Jump size of the loss function at $c^* \in \mathcal{M}$

$$\Delta l(c^*) = \liminf_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) - \limsup_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) = \mathbb{1}'(\bar{x}(c^*) - \underline{x}(c^*)) = \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\}$$

Maximal norm of a jump discontinuity

$$\max_{c \in \mathbb{R}^n} \|\bar{x}(c) - \underline{x}(c)\|_p^p = \left(\min_k \frac{w_k}{\pi_k} \right)^p \|\pi\|_p^p$$

Jump discontinuity as a financial breakdown

A jump discontinuity means that even a slight change in the asset/shock value c may lead to a catastrophic aggregated loss and to sudden defaults of several nodes.

Loss function

- Consider shock ε that lowers the value of the external asset from c to $c - \varepsilon$;
- Loss function is: $l = \mathbb{1}'(\varepsilon + w - x)$

Jump size of the loss function at $c^* \in \mathcal{M}$

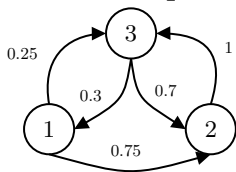
$$\Delta l(c^*) = \liminf_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) - \limsup_{\substack{c \in \mathcal{A} \\ c \rightarrow c^*}} l(c) = \mathbb{1}'(\bar{x}(c^*) - \underline{x}(c^*)) = \min_k \left\{ \frac{\nu_k}{\pi_k} \right\} + \min_k \left\{ \frac{w_k - \nu_k}{\pi_k} \right\}$$

Maximal norm of a jump discontinuity

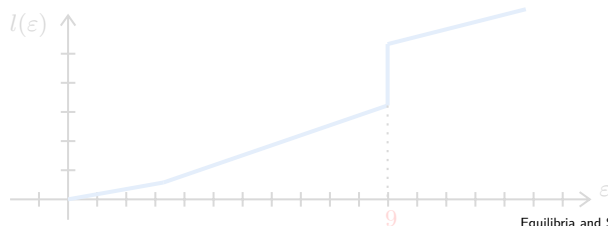
$$\max_{c \in \mathbb{R}^n} \|\bar{x}(c) - \underline{x}(c)\|_p^p = \left(\min_k \frac{w_k}{\pi_k} \right)^p \|\pi\|_p^p$$

Example

Consider the network below with $P = \begin{bmatrix} 0 & 0.75 & 0.25 \\ 0 & 0 & 1 \\ 0.3 & 0.7 & 0 \end{bmatrix}$ and $w = \begin{bmatrix} 5 \\ 3 \\ 2 \end{bmatrix}$.

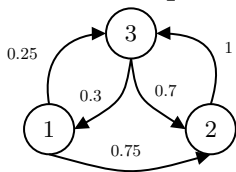


Consider an initial asset $c = [5, 2, 2]'$ and a total shock magnitude $\varepsilon \in [0, 12]$ that hits all nodes uniformly, i.e. $c(\varepsilon) = c - \varepsilon[\frac{1}{3}, \frac{1}{3}, \frac{1}{3}]'$. We expect a jump discontinuity when $\mathbf{1}'c(\varepsilon) = 0 \implies \varepsilon = 9$.

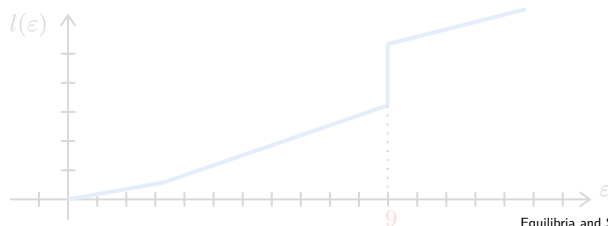


Example

Consider the network below with $P = \begin{bmatrix} 0 & 0.75 & 0.25 \\ 0 & 0 & 1 \\ 0.3 & 0.7 & 0 \end{bmatrix}$ and $w = \begin{bmatrix} 5 \\ 3 \\ 2 \end{bmatrix}$.

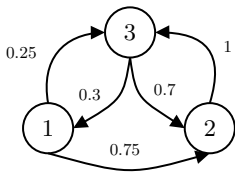


Consider an initial asset $c = [5, 2, 2]'$ and a total shock magnitude $\varepsilon \in [0, 12]$ that hits all nodes uniformly, i.e. $c(\varepsilon) = c - \varepsilon[\frac{1}{3}, \frac{1}{3}, \frac{1}{3}]'$. We expect a jump discontinuity when $\mathbf{1}'c(\varepsilon) = 0 \implies \varepsilon = 9$.

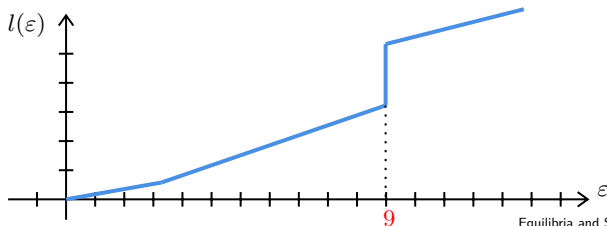


Example

Consider the network below with $P = \begin{bmatrix} 0 & 0.75 & 0.25 \\ 0 & 0 & 1 \\ 0.3 & 0.7 & 0 \end{bmatrix}$ and $w = \begin{bmatrix} 5 \\ 3 \\ 2 \end{bmatrix}$.



Consider an initial asset $c = [5, 2, 2]'$ and a total shock magnitude $\varepsilon \in [0, 12]$ that hits all nodes uniformly, i.e. $c(\varepsilon) = c - \varepsilon[\frac{1}{3}, \frac{1}{3}, \frac{1}{3}]'$. We expect a jump discontinuity when $\mathbf{1}'c(\varepsilon) = 0 \implies \varepsilon = 9$.



Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);

Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);

Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);

Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);



Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);



Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);



Main Results

- Sufficient and necessary condition for Uniqueness of clearing vectors;
- Systemic risk measures and existence of critical shocks;
- Structure of solutions with respect to the topological property of the network.

Ongoing Research

- Optimal policies for risk reduction;
- Analytical results on particular topologies and random graphs;
- Continuous Model.
- Model extensions (fire sales, bankruptcy costs, cross holdings, etc...);



Thank you!