

Noise-induced spatial pattern formation

Stefania Scarsoglio¹

Francesco Laio¹ Paolo D'Odorico² Luca Ridolfi¹

¹Department of Hydraulics, Politecnico di Torino, Torino, Italy

²Department of Environmental Sciences, University of Virginia, Charlottesville, Virginia, USA

ESF Workshop

Self-organised ecogeomorphic systems: confronting models with
data for land-degradation in drylands

07-10 June 2010, Potsdam, Germany

Outline

1 Introduction

Outline

- 1 Introduction
- 2 Additive noise

Outline

- 1 Introduction
- 2 Additive noise
- 3 Multiplicative noise

Outline

- 1 Introduction
- 2 Additive noise
- 3 Multiplicative noise
- 4 Non-linear dynamics

Outline

- 1 Introduction
- 2 Additive noise
- 3 Multiplicative noise
- 4 Non-linear dynamics
- 5 Temporal forcing terms

Outline

- 1 Introduction
- 2 Additive noise
- 3 Multiplicative noise
- 4 Non-linear dynamics
- 5 Temporal forcing terms
- 6 Conclusions

Spatial patterns

- Patterns are widely present in natural dynamical systems:
⇒ hydrodynamic systems (e.g. Rayleigh-Bénard convection), plant ecosystems (e.g. dryland and riparian vegetation), biochemical and neural systems, etc;

Spatial patterns

- Patterns are widely present in natural dynamical systems:
⇒ hydrodynamic systems (e.g. Rayleigh-Bénard convection), plant ecosystems (e.g. dryland and riparian vegetation), biochemical and neural systems, etc;
- Useful information on the processes causing changes of the system. For example, vegetation patterns have been related to:

Spatial patterns

- Patterns are widely present in natural dynamical systems:
⇒ hydrodynamic systems (e.g. Rayleigh-Bénard convection), plant ecosystems (e.g. dryland and riparian vegetation), biochemical and neural systems, etc;
- Useful information on the processes causing changes of the system. For example, vegetation patterns have been related to:
 - the nature of the interactions among plant individuals (*Lefever & Lejeune 1997, Barbier et al. 2007*);

Spatial patterns

- Patterns are widely present in natural dynamical systems:
⇒ hydrodynamic systems (e.g. Rayleigh-Bénard convection), plant ecosystems (e.g. dryland and riparian vegetation), biochemical and neural systems, etc;
- Useful information on the processes causing changes of the system. For example, vegetation patterns have been related to:
 - the nature of the interactions among plant individuals (*Lefever & Lejeune 1997, Barbier et al. 2007*);
 - the landscape's susceptibility to desertification (*von Hardenberg et al. 2001, D'Odorico et al. 2005*).

Spatial patterns

- Patterns are widely present in natural dynamical systems:
 - ⇒ hydrodynamic systems (e.g. Rayleigh-Bénard convection), plant ecosystems (e.g. dryland and riparian vegetation), biochemical and neural systems, etc;
- Useful information on the processes causing changes of the system. For example, vegetation patterns have been related to:
 - the nature of the interactions among plant individuals (*Lefever & Lejeune 1997, Barbier et al. 2007*);
 - the landscape's susceptibility to desertification (*von Hardenberg et al. 2001, D'Odorico et al. 2005*).
- Deterministic models have been studied for quite a long time (*Turing 1952, Cross & Hohenberg 1993*) with a number of applications to environmental processes (*Borgogno et al. 2009, von Hardenberg et al. 2010, Manor & Shnerb 2008, Couteron & Lejeune 2001, Rietkerk & Van de Koppel 2008, Kefi et al. 2007, Lefever et al. 2009*).

Noise-induced pattern formation

- **Stochastic models** have only been developed more recently (*Garcia & Ojalvo 1999, Sagues et al. 2007*): patterns can emerge as a result of noisy fluctuations.

Noise-induced pattern formation

- **Stochastic models** have only been developed more recently (*Garcia & Ojalvo 1999, Sagues et al. 2007*): patterns can emerge as a result of noisy fluctuations.
⇒ **An increase of the noise can produce a more regular behaviour** (*counterintuitive!*).

Noise-induced pattern formation

- **Stochastic models** have only been developed more recently (*Garcia & Ojalvo 1999, Sagues et al. 2007*): patterns can emerge as a result of noisy fluctuations.
⇒ **An increase of the noise can produce a more regular behaviour** (*counterintuitive!*).
- Models of noise-induced pattern formation mainly involve multiplicative noise (*Van den Broeck et al. 1994, Garcia & Ojalvo 1996, Sieber et al. 2007*) along with a high-order diffusion term (*Garcia & Ojalvo 1993*);

Noise-induced pattern formation

- **Stochastic models** have only been developed more recently (*Garcia & Ojalvo 1999, Sagues et al. 2007*): patterns can emerge as a result of noisy fluctuations.
⇒ **An increase of the noise can produce a more regular behaviour** (*counterintuitive!*).
- Models of noise-induced pattern formation mainly involve multiplicative noise (*Van den Broeck et al. 1994, Garcia & Ojalvo 1996, Sieber et al. 2007*) along with a high-order diffusion term (*Garcia & Ojalvo 1993*);
- Additive noise has often been investigated in non-linear models (*Zaikin & Schimansky-Geier 1998, Dutta et al. 2005*), and with the concurrent action of a multiplicative noise (*Landa et al. 1998, Zaikin et al. 1999*);

Noise-induced pattern formation

- **Stochastic models** have only been developed more recently (*Garcia & Ojalvo 1999, Sagues et al. 2007*): patterns can emerge as a result of noisy fluctuations.
⇒ **An increase of the noise can produce a more regular behaviour** (*counterintuitive!*).
- Models of noise-induced pattern formation mainly involve multiplicative noise (*Van den Broeck et al. 1994, Garcia & Ojalvo 1996, Sieber et al. 2007*) along with a high-order diffusion term (*Garcia & Ojalvo 1993*);
- Additive noise has often been investigated in non-linear models (*Zaikin & Schimansky-Geier 1998, Dutta et al. 2005*), and with the concurrent action of a multiplicative noise (*Landa et al. 1998, Zaikin et al. 1999*);
- Since these models use complicated non-linear terms for the local dynamics and the multiplicative noise terms, their process-based interpretation is often not straightforward.

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;
 - a diffusive spatial coupling term, which provides spatial coherence.

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;
 - a diffusive spatial coupling term, which provides spatial coherence.
- Gaussian white (in time and space) noise:

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;
 - a diffusive spatial coupling term, which provides spatial coherence.
- Gaussian white (in time and space) noise:
 - Valid assumption for the unavoidable randomness of real systems;

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;
 - a diffusive spatial coupling term, which provides spatial coherence.
- Gaussian white (in time and space) noise:
 - Valid assumption for the unavoidable randomness of real systems;
 - Simplification of analytical and numerical calculations;

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;
 - a diffusive spatial coupling term, which provides spatial coherence.
- Gaussian white (in time and space) noise:
 - Valid assumption for the unavoidable randomness of real systems;
 - Simplification of analytical and numerical calculations;
 - Rich literature (unlike Gaussian colored or dichotomous noise).

Stochastic mechanisms

- Overview of the main stochastic processes related to the presence of a Gaussian white noise. In particular, we focus on the fundamental components able to induce spatial coherence:
 - a linear local dynamics, which damps the system to zero;
 - an additive noise, which avoids the deterministic dynamics to decay;
 - a diffusive spatial coupling term, which provides spatial coherence.
- Gaussian white (in time and space) noise:
 - Valid assumption for the unavoidable randomness of real systems;
 - Simplification of analytical and numerical calculations;
 - Rich literature (unlike Gaussian colored or dichotomous noise).
- We call **patterned** a field that exhibits an ordered state with organized spatial structures. This definition is often adopted in the environmental sciences, where the concomitance of many processes can prevent the organization of the system with a clear dominant wavelength.

Stochastic modeling: general framework

Temporal evolution of the state variable ϕ at any point $\mathbf{r} = (x, y)$:

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi] + h(\phi)F(t)$$

Stochastic modeling: general framework

Temporal evolution of the state variable ϕ at any point $\mathbf{r} = (x, y)$:

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi] + h(\phi)F(t)$$

- $f(\phi)$: **local dynamics** (in the absence of spatial interactions with other points of the domain) \Rightarrow **local rate of increase/decrease** (*vegetation mortality rate*);

Stochastic modeling: general framework

Temporal evolution of the state variable ϕ at any point $\mathbf{r} = (x, y)$:

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi] + h(\phi)F(t)$$

- $f(\phi)$: **local dynamics** (in the absence of spatial interactions with other points of the domain) \Rightarrow **local rate of increase/decrease** (*vegetation mortality rate*);
- $g(\phi)\xi$: **noise component**, ξ zero-mean Gaussian white noise with correlation $\langle \xi(x, t)\xi(x', t') \rangle = s\delta(x - x')\delta(t - t')$ and intensity $s \Rightarrow$ **environmental disturbances** (*fires, rain, etc*);

Stochastic modeling: general framework

Temporal evolution of the state variable ϕ at any point $\mathbf{r} = (x, y)$:

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi] + h(\phi)F(t)$$

- $f(\phi)$: **local dynamics** (in the absence of spatial interactions with other points of the domain) \Rightarrow **local rate of increase/decrease** (*vegetation mortality rate*);
- $g(\phi)\xi$: **noise component**, ξ zero-mean Gaussian white noise with correlation $\langle \xi(x, t)\xi(x', t') \rangle = s\delta(x - x')\delta(t - t')$ and intensity $s \Rightarrow$ **environmental disturbances** (*fires, rain, etc*);
- $D\mathcal{L}[\phi]$: **spatial coupling**. Laplacian (∇^2) or the Swift-Hohenberg $(\nabla^2 + k_0^2)^2$ coupling (k_0 : selected wavenumber), D is the strength of the spatial coupling \Rightarrow **diffusion mechanisms** (*vegetation spatial interactions*);

Stochastic modeling: general framework

Temporal evolution of the state variable ϕ at any point $\mathbf{r} = (x, y)$:

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi] + h(\phi)F(t)$$

- $f(\phi)$: **local dynamics** (in the absence of spatial interactions with other points of the domain) \Rightarrow **local rate of increase/decrease** (*vegetation mortality rate*);
- $g(\phi)\xi$: **noise component**, ξ zero-mean Gaussian white noise with correlation $\langle \xi(x, t)\xi(x', t') \rangle = s\delta(x - x')\delta(t - t')$ and intensity $s \Rightarrow$ **environmental disturbances** (*fires, rain, etc*);
- $D\mathcal{L}[\phi]$: **spatial coupling**. Laplacian (∇^2) or the Swift-Hohenberg ($\nabla^2 + k_0^2$)² coupling (k_0 : selected wavenumber), D is the strength of the spatial coupling \Rightarrow **diffusion mechanisms** (*vegetation spatial interactions*);
- $h(\phi)F(t)$: **time-dependent forcing term**, which can be modulated by a function, $h(\phi)$, of the local state of the system \Rightarrow **seasonal phenomena** (*phreatic aquifer*).

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;
- ξ : white Gaussian zero-mean noise \Rightarrow **Random fluctuations**;

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;
- ξ : white Gaussian zero-mean noise \Rightarrow **Random fluctuations**;
- **Noise-induced pattern formation** \Rightarrow the deterministic dynamics ($\xi = 0$) do not exhibit patterns;

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;
- ξ : white Gaussian zero-mean noise \Rightarrow **Random fluctuations**;
- **Noise-induced pattern formation** \Rightarrow the deterministic dynamics ($\xi = 0$) do not exhibit patterns;
- Additive noise does not play the role of a precursor of a phase transition in a deterministic system close to a bifurcation point, since there is no bifurcation in the deterministic dynamics;

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;
- ξ : white Gaussian zero-mean noise \Rightarrow **Random fluctuations**;
- **Noise-induced pattern formation** \Rightarrow the deterministic dynamics ($\xi = 0$) do not exhibit patterns;
- Additive noise does not play the role of a precursor of a phase transition in a deterministic system close to a bifurcation point, since there is no bifurcation in the deterministic dynamics;
- Analytical tools:
 - Mean-field analysis (MFA): analytical expression of the pdf at steady state. Classic MFA and a corrected version;

Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;
- ξ : white Gaussian zero-mean noise \Rightarrow **Random fluctuations**;
- **Noise-induced pattern formation** \Rightarrow the deterministic dynamics ($\xi = 0$) do not exhibit patterns;
- Additive noise does not play the role of a precursor of a phase transition in a deterministic system close to a bifurcation point, since there is no bifurcation in the deterministic dynamics;
- Analytical tools:
 - Mean-field analysis (MFA): analytical expression of the pdf at steady state. Classic MFA and a corrected version;
 - Structure function (SF): prognostic tool able to assess the presence of a selected wavelength in the spatial field;

Scarsoglio, Laio, Ridolfi, D'Odorico, submitted *Phys. Rev. Lett.* 2010.

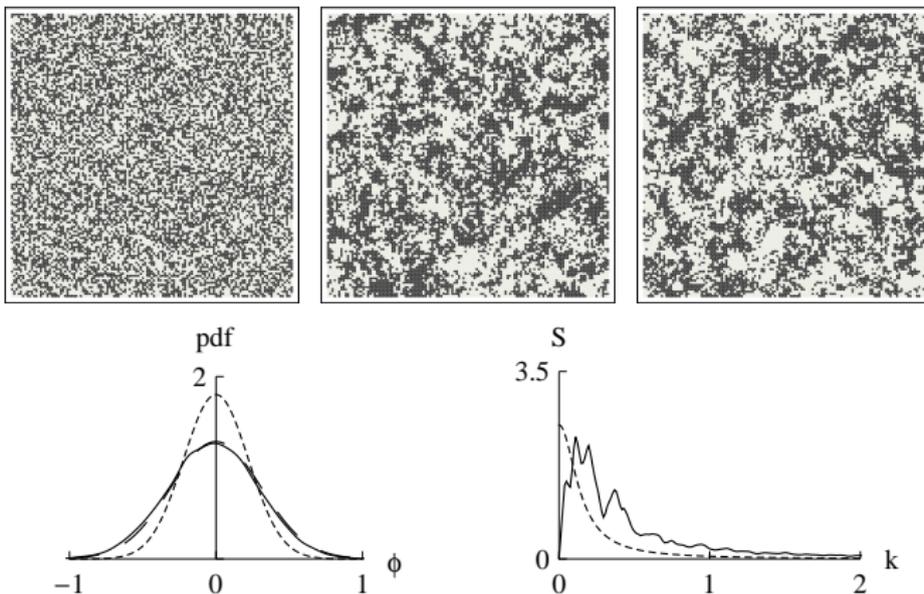
Simple stochastic model

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi$$

- $-\phi$: linear decreasing term \Rightarrow **Deterministic local dynamics**;
- $D\nabla^2 \phi$: linear Laplacian (diffusive) operator \Rightarrow **Spatial interactions**;
- ξ : white Gaussian zero-mean noise \Rightarrow **Random fluctuations**;
- **Noise-induced pattern formation** \Rightarrow the deterministic dynamics ($\xi = 0$) do not exhibit patterns;
- Additive noise does not play the role of a precursor of a phase transition in a deterministic system close to a bifurcation point, since there is no bifurcation in the deterministic dynamics;
- Numerical simulations:
 - Heun's predictor corrector scheme, 2D square lattice with 128x128 sites;
 - periodic BCs, ICs given by uniformly distributed random numbers between $[-0.01, 0.01]$.

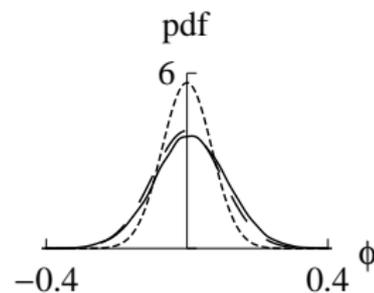
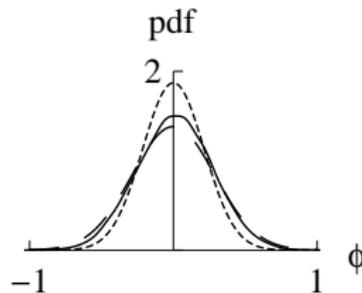
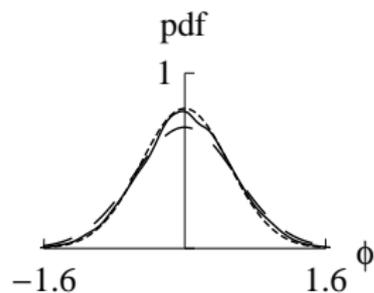
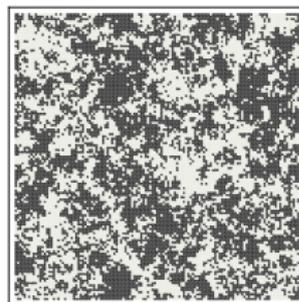
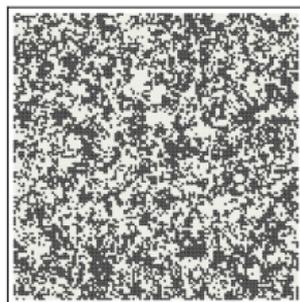
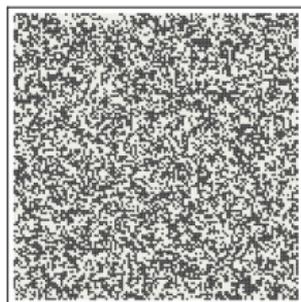
Scarsoglio, Laio, Ridolfi, D'Odorico, submitted *Phys. Rev. Lett.* 2010.

Steady and multiscale patterns



(top) Numerical simulation of ϕ at $t = 0, 10, 100$, $D = 50$, $s = 5$. (below) Pdf (solid: numerical simulation, dotted: classic MFA, dashed: corrected MFA) and azimuthal-averaged power spectrum S (solid: numerical simulation, dotted: SF) of ϕ at $t = 100$.

Role of D



(top) Numerical simulation of ϕ at $t = 100$, $s = 1$, $D = 1, 10, 100$ (left to right). (below) Pdf of ϕ (solid: numerical simulation, dotted: classic MFA, dashed: corrected MFA).

Comparison with vegetation pattern

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi + \mu$$

Comparison with vegetation pattern

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi + \mu$$

- $-\phi$: local linear decreasing dynamics of the existing vegetation;

Comparison with vegetation pattern

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi + \mu$$

- $-\phi$: local linear decreasing dynamics of the existing vegetation;
- $D\nabla^2 \phi$: vegetation's ability to develop spatial interactions;

Comparison with vegetation pattern

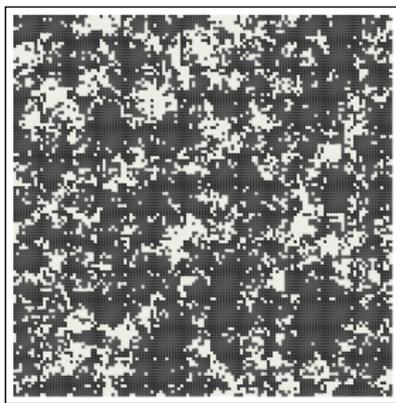
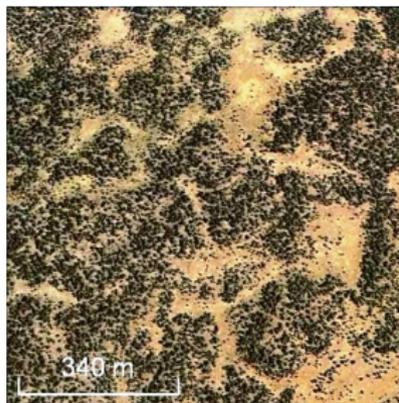
$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi + \mu$$

- $-\phi$: local linear decreasing dynamics of the existing vegetation;
- $D\nabla^2 \phi$: vegetation's ability to develop spatial interactions;
- $\xi + \mu$: random rain water availability;

Comparison with vegetation pattern

$$\frac{\partial \phi}{\partial t} = -\phi + D\nabla^2 \phi + \xi + \mu$$

- $-\phi$: local linear decreasing dynamics of the existing vegetation;
- $D\nabla^2 \phi$: vegetation's ability to develop spatial interactions;
- $\xi + \mu$: random rain water availability;



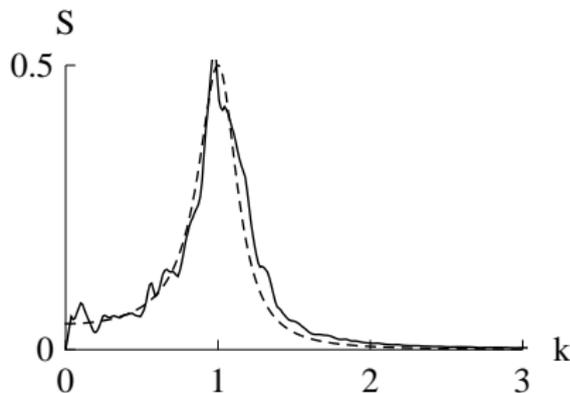
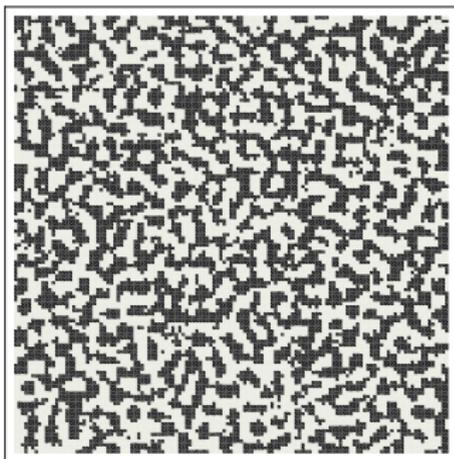
(left) Aerial photograph of vegetation pattern in New Mexico ($34^\circ 47'N$, $108^\circ 21'O$) and
 (right) numerical simulation at $t = 100$, $a = -1$, $D = 80$, $s = 2$, $\mu = 0.1$.

Steady and periodic patterns

$$\frac{\partial \phi}{\partial t} = -\phi - D(\nabla^2 + k_0^2)^2 \phi + \xi$$

Steady and periodic patterns

$$\frac{\partial \phi}{\partial t} = -\phi - D(\nabla^2 + k_0^2)^2 \phi + \xi$$



(left) Numerical simulation of ϕ at $t = 100$, $s = 1$, $D = 10$, $k_0 = 1$. (right) Azimuthal-averaged power spectrum S (solid: numerical simulation, dotted: SF).

Short-term instability and spatial coupling

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi]$$

Short-term instability and spatial coupling

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi]$$

- The cooperation between multiplicative noise and spatial coupling is based on two key actions:

Short-term instability and spatial coupling

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi]$$

- The cooperation between multiplicative noise and spatial coupling is based on two key actions:
 - The multiplicative noise component temporarily destabilizes the homogeneous stable state of the underlying deterministic dynamics;

Short-term instability and spatial coupling

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi]$$

- The cooperation between multiplicative noise and spatial coupling is based on two key actions:
 - The multiplicative noise component temporarily destabilizes the homogeneous stable state of the underlying deterministic dynamics;
 - The spatial coupling exploits this initial instability, giving rise to the pattern and stabilizing it.

Short-term instability and spatial coupling

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi]$$

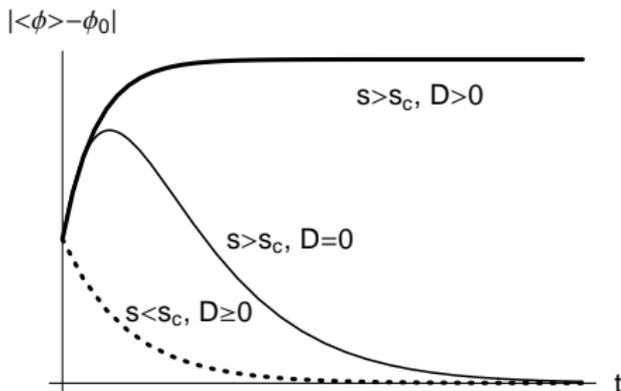
- The cooperation between multiplicative noise and spatial coupling is based on two key actions:
 - The multiplicative noise component temporarily destabilizes the homogeneous stable state of the underlying deterministic dynamics;
 - The spatial coupling exploits this initial instability, giving rise to the pattern and stabilizing it.
- For $s < s_c$, the system remains blocked in the disordered phase and no patterns occur. Only transiently, the spatial coupling might be able to induce patterns that fade away at steady state;

Short-term instability and spatial coupling

$$\frac{\partial \phi}{\partial t} = f(\phi) + g(\phi)\xi(\mathbf{r}, t) + D\mathcal{L}[\phi]$$

- The cooperation between multiplicative noise and spatial coupling is based on two key actions:
 - The multiplicative noise component temporarily destabilizes the homogeneous stable state of the underlying deterministic dynamics;
 - The spatial coupling exploits this initial instability, giving rise to the pattern and stabilizing it.
- For $s < s_c$, the system remains blocked in the disordered phase and no patterns occur. Only transiently, the spatial coupling might be able to induce patterns that fade away at steady state;
- For $s > s_c$, the spatial term can take advantage from the noise-induced short-term instability and prevents the decay to zero. The spatial coupling traps the system in a new ordered state.

Short-term instability and spatial coupling



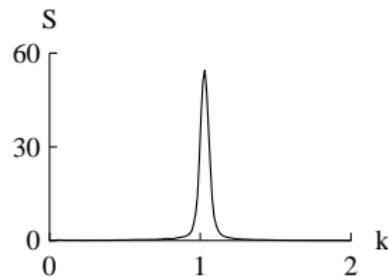
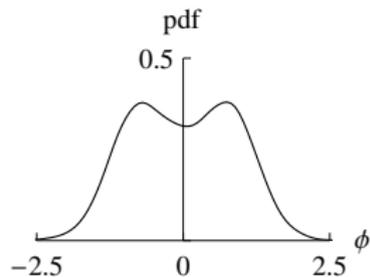
- For $s < s_c$, the system remains blocked in the disordered phase and no patterns occur. Only transiently, the spatial coupling might be able to induce patterns that fade away at steady state;
- For $s > s_c$, the spatial term can take advantage from the noise-induced short-term instability and prevents the decay to zero. The spatial coupling traps the system in a new ordered state.

Steady and periodic patterns

$$\frac{\partial \phi}{\partial t} = -\phi - \phi^3 + \phi \xi - D(\nabla^2 + k_0^2)^2 \phi$$

Steady and periodic patterns

$$\frac{\partial \phi}{\partial t} = -\phi - \phi^3 + \phi \xi - D(\nabla^2 + k_0^2)^2 \phi$$



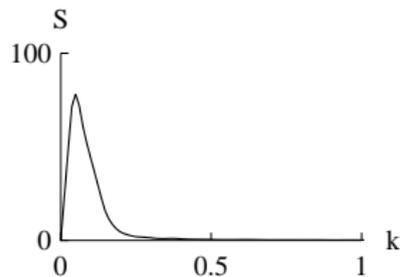
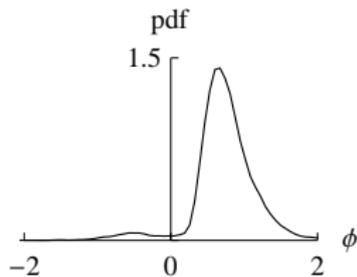
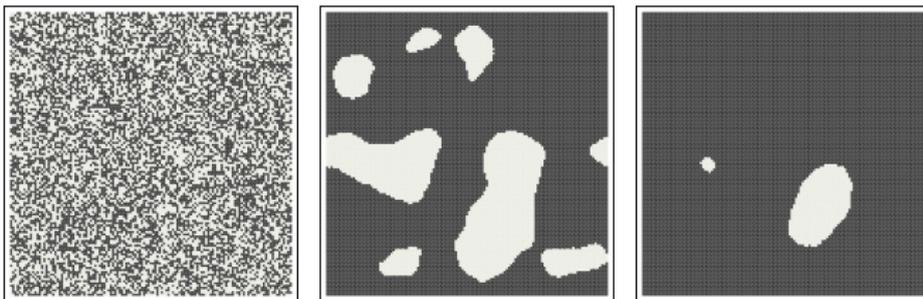
(top) Numerical simulation of the spatial field ϕ at $t = 0, 10, 100$, with $D = 15$, $s = 5$, $k_0 = 1$. (below) Pdf and azimuthal-averaged power spectrum S at $t = 100$.

Transient and multiscale patterns

$$\frac{\partial \phi}{\partial t} = -\phi - \phi^3 + \phi \xi + D \nabla^2 \phi$$

Transient and multiscale patterns

$$\frac{\partial \phi}{\partial t} = -\phi - \phi^3 + \phi \xi + D \nabla^2 \phi$$



(top) Numerical simulation of the spatial field ϕ at $t = 0, 10, 40$, with $D = 20$, $s = 4$.

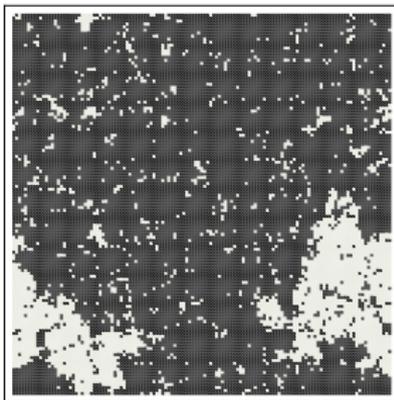
(below) Pdf and azimuthal-averaged power spectrum S at $t = 40$.

Non-linear dynamics

$$\frac{\partial \phi}{\partial t} = -\phi(1 + \phi^2)^2 + (1 + \phi^2)\xi + D\mathcal{L}[\phi]$$

Non-linear dynamics

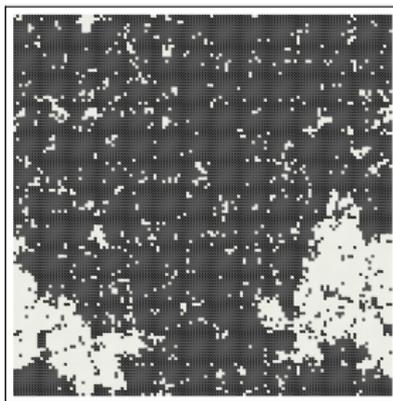
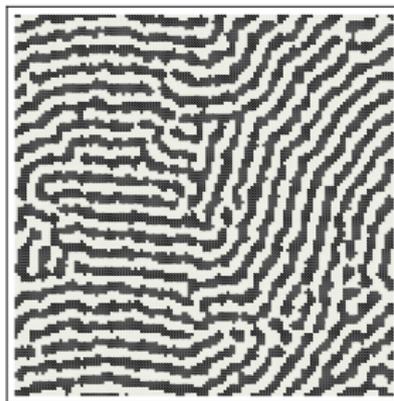
$$\frac{\partial \phi}{\partial t} = -\phi(1 + \phi^2)^2 + (1 + \phi^2)\xi + D\mathcal{L}[\phi]$$



Numerical simulation of ϕ . (left) Swift-Hohenberg spatial coupling at $t = 100$, $D = 15$, $s = 5$, $k_0 = 1$, and (right) Laplacian spatial coupling at $t = 200$, $D = 20$, $s = 4$.

Non-linear dynamics

$$\frac{\partial \phi}{\partial t} = -\phi(1 + \phi^2)^2 + (1 + \phi^2)\xi + D\mathcal{L}[\phi]$$



Numerical simulation of ϕ . (left) Swift-Hohenberg spatial coupling at $t = 100$, $D = 15$, $s = 5$, $k_0 = 1$, and (right) Laplacian spatial coupling at $t = 200$, $D = 20$, $s = 4$.

Non-linearities do not change the pattern scenario, provided that the interplay between short-term instability and spatial coupling remains the same.

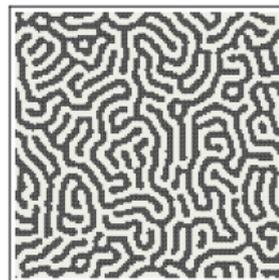
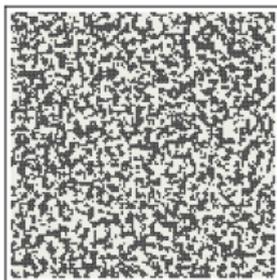
Time oscillating patterns

$$\frac{\partial \phi}{\partial t} = [-k + \alpha \sin(\omega t)]\phi - \phi^3 - D(k_0^2 + \nabla^2)^2 \phi + \xi$$

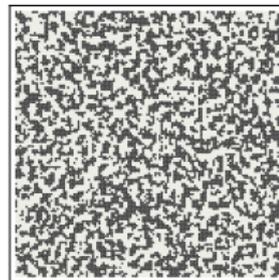
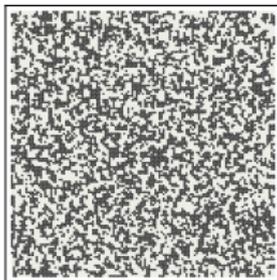
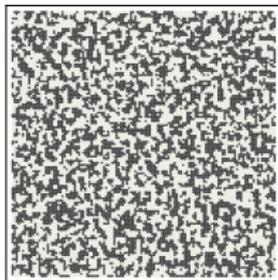
Time oscillating patterns

$$\frac{\partial \phi}{\partial t} = [-k + \alpha \sin(\omega t)]\phi - \phi^3 - D(k_0^2 + \nabla^2)^2 \phi + \xi$$

$s = 0.025$



$s = 2.5$



$t = 110$

$t = 140$

$t = 195$

Numerical simulation of ϕ with $\alpha = k_0 = 1$, $k = 0.1$, $\omega/2\pi = 0.012$, and $D = 1$.

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:
 - A **deterministic local dynamics**, which tends to drive the field variable to a uniform steady state (this component is not able to explain pattern formation);

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:
 - A **deterministic local dynamics**, which tends to drive the field variable to a uniform steady state (this component is not able to explain pattern formation);
 - An **additive noise** able to maintain the dynamics away from the uniform steady state;

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:
 - A **deterministic local dynamics**, which tends to drive the field variable to a uniform steady state (this component is not able to explain pattern formation);
 - An **additive noise** able to maintain the dynamics away from the uniform steady state;
 - A **spatial coupling term** which provides spatial coherence.

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:
 - A **deterministic local dynamics**, which tends to drive the field variable to a uniform steady state (this component is not able to explain pattern formation);
 - An **additive noise** able to maintain the dynamics away from the uniform steady state;
 - A **spatial coupling term** which provides spatial coherence.
- For high enough multiplicative noise intensity, the spatial coupling exploits the initial instability giving rise to ordered structures;

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:
 - A **deterministic local dynamics**, which tends to drive the field variable to a uniform steady state (this component is not able to explain pattern formation);
 - An **additive noise** able to maintain the dynamics away from the uniform steady state;
 - A **spatial coupling term** which provides spatial coherence.
- For high enough multiplicative noise intensity, the spatial coupling exploits the initial instability giving rise to ordered structures;
- The presence of a temporal periodicity promotes oscillating patterns which periodically emerge and disappear;

Conclusions

- Three main components play a fundamental role in the mechanism of noise-induced pattern formation:
 - A **deterministic local dynamics**, which tends to drive the field variable to a uniform steady state (this component is not able to explain pattern formation);
 - An **additive noise** able to maintain the dynamics away from the uniform steady state;
 - A **spatial coupling term** which provides spatial coherence.
- For high enough multiplicative noise intensity, the spatial coupling exploits the initial instability giving rise to ordered structures;
- The presence of a temporal periodicity promotes oscillating patterns which periodically emerge and disappear;
- Since noisy fluctuations are always present in real systems and pattern formation, here described, is **completely noise-induced**, randomness can actually promote spatial coherence in different environmental processes.